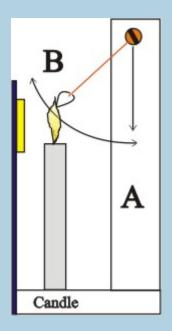
#### **Curie Temperature**

Neil McGlohon & Nathan Beck (2012) Tim Corbly & Richard Mihelic (2013)

#### **The Curie Point**

- Curie point, also called Curie Temperature, temperature at which certain magnetic materials undergo a sharp change in their magnetic properties.
- This temperature is named for the French physicist Pierre Curie, who in 1895 discovered the laws that relate some magnetic properties to change in temperature.
- At low temperatures, magnetic dipoles are aligned. Above the curie point, random thermal motions nudge dipoles out of alignment.

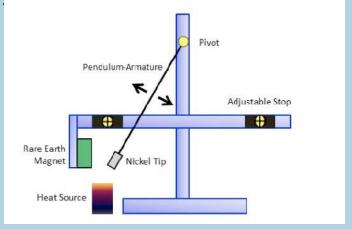


An example of a curie pendulum which utilizes the effects of heat on a ferromagnetic substance's magnetization. The motion is periodic and follows the heating/cooling process of the swinging bob.

#### **Curie Pendulum**

- The heat engine uses a principle of magnetism discovered by Curie. He studied the effects of temperature on magnetism.
- Ferromagnetism covers the field of normal magnetism that people typically associate with magnets. All normal magnets and the material that are attracted to magnets are ferromagnetic materials.
- Pierre Curie discovered that ferromagnetic materials have a critical temperature at which the material loses their ferromagnetic behavior. This is known as its Curie Point.
- Once the material reaches the Curie Point, it will lose some of its magnetic properties until it cools away from the heat source and regains its magnetic properties. It is then pulled into the heat source again by the engine magnet to

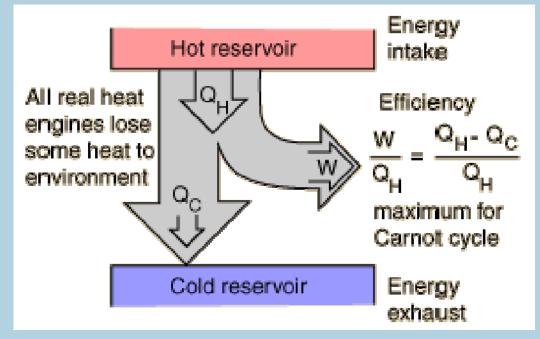
cycle through again.



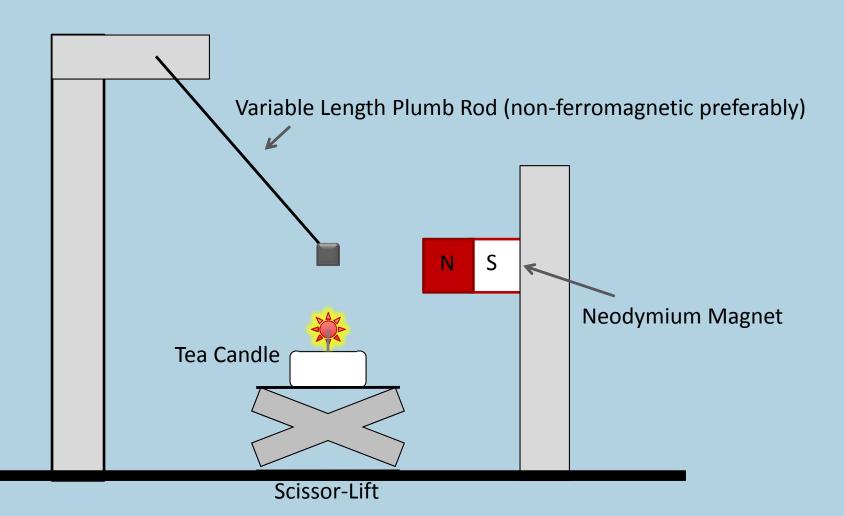
The heat source could be a flame or even a light depending on the material of the bob.

## **Heat Engines**

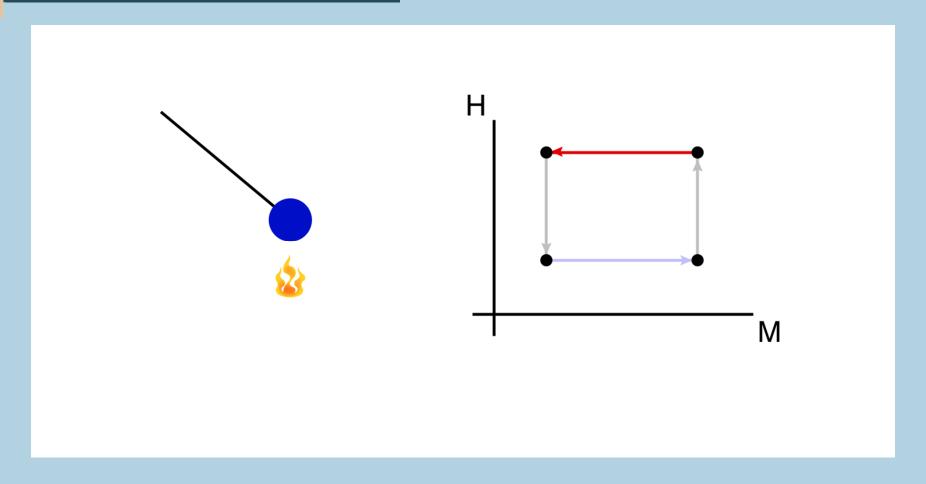
- A heat engine transfers energy from a hot reservoir to a cold reservoir, converting some of it into mechanical work.
- No engine operating between two heat reservoirs can be more efficient than a Carnot engine operating between the same reservoirs.
- Examples of heat engines:
  - Curie point
  - Stirling Engine
  - Steam engine
  - Elastic engine



# **Diagram of Apparatus**



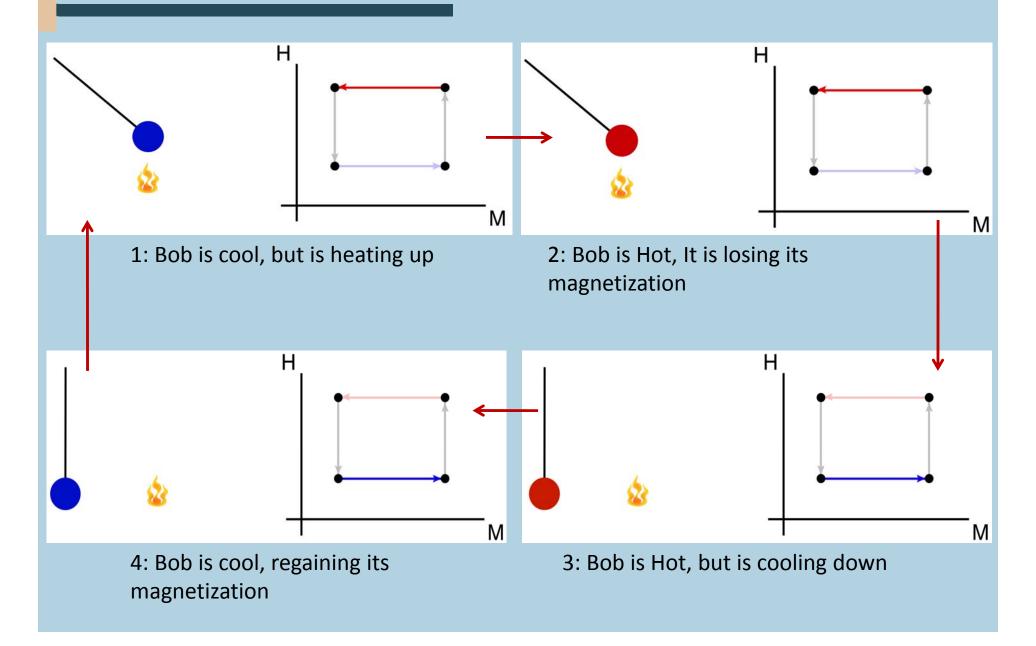
#### How it works!



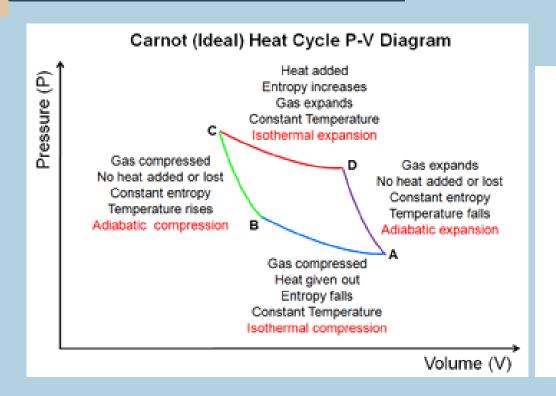
H: magnetic field intensity

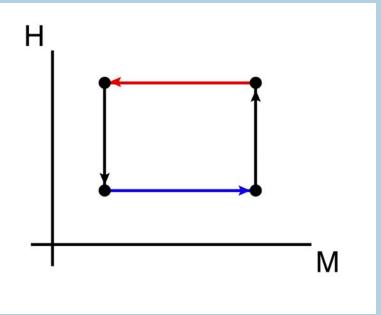
M: magnetization

#### How it works!



# **Carnot Cycle PV Diagram**

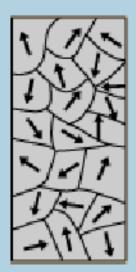




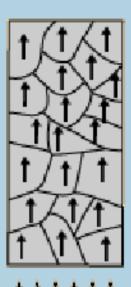
Our heat engine is not exactly a Carnot cycle, however there are similarities between it and our HM diagram.

## Paramagnetism vs. Ferromagnetism

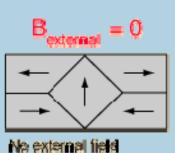
- Materials are made up of magnetic domains, which contain atomic dipoles coupled together in some direction.
- Typically, these domains are aligned in random directions, and so there is no overall magnetic direction.
- In the presence of a magnetic field, domains parallel to the field grow while others shrink.
- Paramagnetic materials have a positive magnetic susceptibility. Ferromagnetic materials have a strong positive susceptibility.
- Ferromagnetic materials can remain magnetized after the external field is removed.

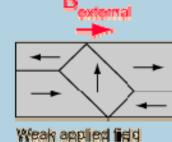


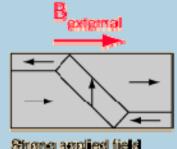
In bulk material the domains usually cancel, leaving the material unmagnetized.











k applied field Strong applied field

#### **The Curie Point**

Material	Curie temperature (K)		
Fe	1043		
Co	1388		
Ni	627		
Gd	293		
Dy	85		
CrBr3	37		
Au2MnA	200		
Cu2MnAl	630		
Cu2MnIn	500		
EuO	77		
EuS	16.5		
MnAs	318		
MnBi	670		
GdC13	2.2		
Fe2B	1015		
MnB	578		



Nickel's curie point is 627 K, this is equivalent to around 354 degrees Celsius. This make it optimal for a flame based Curie Pendulum.

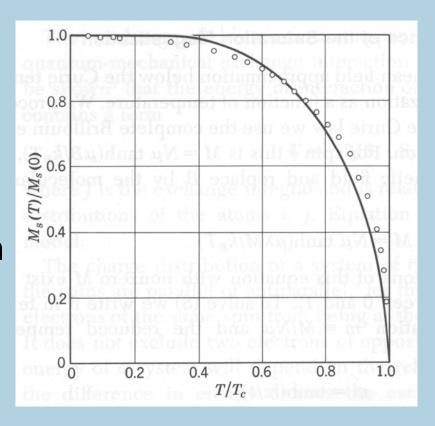


Gadolinium has a Curie Temperature of 293 K. This is equivalent to around 20 degrees Celsius. This makes for a good material in a light based Curie Pendulum.

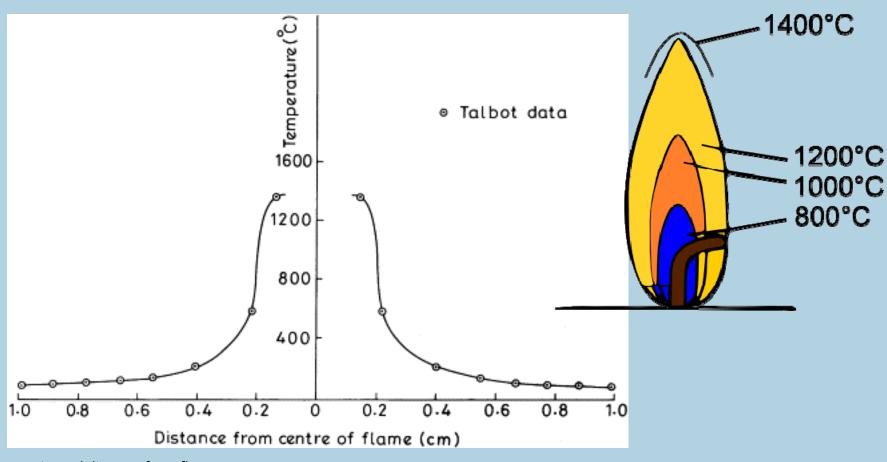
Data from F. Keffer, Handbuch der Physik, 18, pt. 2, New York: Springer-Verlag, 1966 and P. Heller, Rep. Progr. Phys., 30, (pt II), 731 (1967)

### **Temperatures of Interest**

- Nickel has a Curie
   Temperature of 627K.
- We expect the bob to follow an oscillatory path that orbits the curie point with a period under 10 seconds (from observation of examples).



## **Candle Temperature Profile**



Horizontal distance from flame:

Source: http://www.sciencedirect.com/science/article/pii/S0143816699000378

## **Neodymium Magnets**

Could we damage the magnet itself with the flame?

Magnet	M <sub>r</sub> (T)	H <sub>ci</sub> (kA/m)	BH <sub>max</sub> (kJ/m <sup>3</sup> )	T <sub>C</sub> (°C)
Nd <sub>2</sub> Fe <sub>14</sub> B (sintered)	1.0-1.4	750–2000	200-440	310-400
Nd <sub>2</sub> Fe <sub>14</sub> B (bonded)	0.6-0.7	600-1200	60-100	310–400
SmCo <sub>5</sub> (sintered)	0.8–1.1	600–2000	120-200	720
Sm(Co, Fe, Cu, Zr) <sub>7</sub> (sintered)	0.9–1.15	450-1300	150-240	800
Alnico (sintered)	0.6–1.4	275	10-88	700-860
Sr-ferrite (sintered)	0.2-0.4	100–300	10-40	450

We could, if the magnet crosses its Curie point, it will permanently lose its magnetization. But from the flame profile in the previous slide the magnet is kept at a safe enough horizontal distance to avoid damage. The magnet stayed cool enough to touch throughout the experiment.

# **Example of Basic Apparatus**

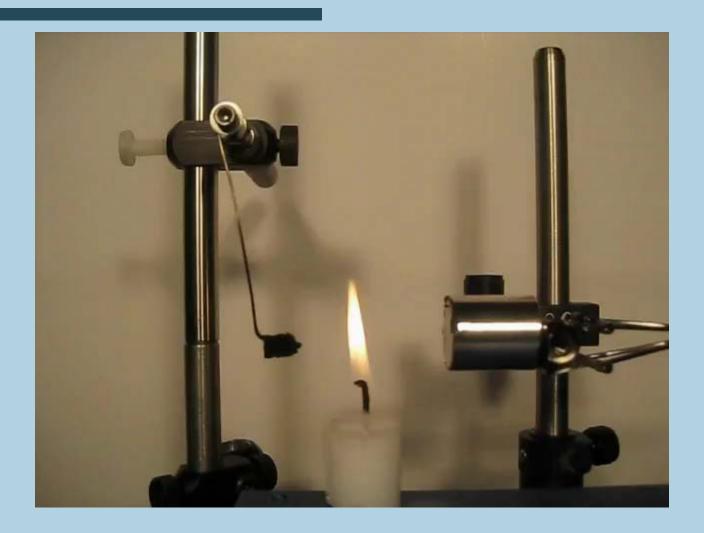


# Mark I



Period of about 7 seconds.

# Mark II



Period of about 5 seconds.

# Stefan-Boltzmann Law - Cooling

 Energy radiated by a blackbody radiator per second per unit area is proportional to the fourth power of the absolute temperature and is given by the Stefan-Boltzemann Law:

$$\frac{P}{A} = \sigma T^4$$

But not every radiator is ideal – in which case the proportionality constant for emissivity is introduced:

(ideal radiator: 
$$e = 1$$
) 
$$\frac{P}{A} = e\sigma T^4$$

## Stefan-Boltzmann Law - Cooling

 If the hot object is radiating energy to its cooler surroundings at temperature T<sub>s</sub> then the total energy radiated is:

$$P = e \sigma A (T^4 - T_s^4)$$

 Our concern with this is the candle soot that builds up on the pendulum bob could affect the emissivity of the nickel and change the properties of the system over time.

## Data - Magnetic Field

Measurements with a magnetic field probe, output a voltage corresponding to two different sweet spots that measured the Axial and Transverse potential at a given point.

X distance: Horizontal distance from edge of magnet. Positive away.

Y distance: vertical distance from center of magnet. Positive down.

State 1, the position of the bob when it is at its maximum magnetic field amplitude.

State 2, the position of the bob after it falls from the magnet.

3 0 0.026 -0.147 2.5 0 0.046 -0.232 2 0 0.080 -0.349 1.5 0 0.149 -0.566 1 1 0 0.273 -0.906 0.5 0 0.476 -1.000 0.25 0 0.700 -0.701 0.25 0 0.094 -1.000 0 0 0 0.904 -1.000 0 0 0.003 -0.160 4 0 0.015 -0.079 5 0 0.009 -0.040 6 0 0 0.006 -0.021 7 0 0.004 -0.005 10 0 0.003 0.110 22 0 0.002 0.002  Zeroed at 22 cm 1 0 0 0.196 -0.732 1 1 1 -0.357 -0.484 1 1 1 -0.249 -0.493 1 2 -0.405 -0.195 1 3 -0.296 -0.044 1 3 -0.296 -0.044 1 1 4 -0.149 0.016 1 5 -0.086 0.029  State 1  X (cm) Y (cm) Axial (V) Transverse (V)  Zeroed at 22 cm  State 2  X (cm) Y (cm) Axial (V) Transverse (V)  Zeroed at 22 cm  State 2  X (cm) Y (cm) Axial (V) Transverse (V)  Transverse (V)					
2.5	Zeroed at 22cm	x-distance (cm)			Transverse (V)
2			-		
1.5					
1 0 0.273 -0.906 0.5 0 0.476 -1.000 0.25 0 0.700 -1.000 0 0 0.904 -1.000 0 0 0.904 -1.000 0 0 0.015 -0.079 1 0 0.005 -0.040 1 0 0 0.005 -0.040 1 0 0 0.006 -0.21 1 7 0 0.004 -0.005 1 0 0 0.002 0.022 0 0 0.002 0.022 0 0 0.002 0.022 0 0 0.002 0.022 0 0 0.002 0.022 0 0 0.003 0.110 1 1 0 0 0.196 -0.732 1 1 1 1 -0.357 -0.484 1 1 1 -0.249 -0.493 1 1 2 -0.405 -0.195 1 1 3.5 -0.199 0.003 1 1 3.5 -0.199 0.003 1 1 3.5 -0.199 0.003 1 1 3 -0.296 -0.044 1 1 4 -0.149 0.016 1 5 -0.086 0.029 1 2 5 -1.002 0.023 0 5 -1.002 0.023 0 5 -1.002 0.023 0 5 -0.253 0 0.05 -0.253 0 0.056 -0.253					
0.5		1.5	0		
0.25		_			-0.906
0					-1.000
3 0 0.030 -0.160 4 0 0.015 -0.079 5 0 0.009 -0.040 6 0 0.006 -0.021 7 0 0.004 -0.005 10 0 0.003 0.110 22 0 0 0.002 0.022  Zeroed at 22 cm 1 0 0 0.196 -0.732 1 1 0 0.357 -0.484 1 1 1 -0.357 -0.484 1 1 1 -0.249 -0.493 1 2 -0.405 -0.195 1 3.5 -0.199 0.003 1 3 3 -0.296 -0.044 1 4 -0.149 0.016 1 5 -0.086 0.029 22 5 -1.002 0.023  State 1  x (cm) y (cm) Axial (V) Transverse (V)  Zeroed at 22 cm  State 2  x (cm) y (cm) Axial (V) Transverse (V)  State 2  x (cm) Axial (V) Transverse (V)  Transverse (V)		0.25	0		-1.000
4		0	0	0.904	-1.000
4					
5       0       0.009       -0.040         6       0       0.006       -0.021         7       0       0.004       -0.005         10       0       0.003       0.110         22       0       0.002       0.022         Zeroed at 22 cm       1       0       0.196       -0.732         1       1       1       -0.357       -0.484         1       1       1       -0.249       -0.493         1       2       -0.405       -0.195         1       3       -0.296       -0.044         1       3       -0.296       -0.044         1       4       -0.149       0.016         1       5       -0.086       0.029         22       5       -1.002       0.023         State 1       7       -0.35       0.056       -0.253         22       -0.35       0.068       -0.289         21       -0.35       0.059       -0.271         22       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       7       Axial (V)       T		3	0	0.030	-0.160
6       0       0.006       -0.021         7       0       0.004       -0.005         10       0       0.003       0.110         22       0       0.002       0.022         Zeroed at 22 cm       0       0.0196       -0.732         1       1       1       -0.357       -0.484         1       1       1       -0.249       -0.493         1       2       -0.405       -0.195         1       3       -0.296       -0.044         1       3       -0.296       -0.044         1       4       -0.149       0.016         1       5       -0.086       0.029         22       5       -1.002       0.023         State 1       y (cm)       Axial (V)       Transverse (V)         2.1       -0.35       0.056       -0.253         2.2       -0.35       0.056       -0.271         22       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       X (cm)       Y (cm)       Axial (V)       Transverse (V)         5.7       0.45		-	0	0.015	-0.079
Total		5	0	0.009	-0.040
10		6	0	0.006	-0.021
Zeroed at 22 cm  1 0 0.002  1 1 0 0.196 -0.732  1 1 1 -0.357 -0.484  1 1 1 -0.249 -0.493  1 2 -0.405 -0.195  1 3.5 -0.199 0.003  1 3 -0.296 -0.044  1 4 -0.149 0.016  1 5 -0.086 0.029  22 5 -1.002 0.023  State 1  x (cm)  y (cm)  Axial (V)  Transverse (V)  2.1 -0.35 0.056 -0.253  2.2 -0.35 0.068 -0.289  2.1 -0.35 0.059 -0.271  2.2 -0.35 0.005 0.026  Zeroed at 22 cm  State 2  x (cm)  y (cm)  Axial (V)  Transverse (V)		7	0	0.004	-0.005
Zeroed at 22 cm  1 0 0.196 -0.732 1 1 1 -0.357 -0.484 1 1 -0.249 -0.493 1 2 -0.405 -0.195 1 3.5 -0.199 0.003 1 3 -0.296 -0.044 1 4 -0.149 0.016 1 5 -0.086 0.029 2 5 -1.002 0.023  State 1  x (cm)  y (cm)  Axial (V)  Transverse (V)  2.1 -0.35 0.068 -0.289 2.1 -0.35 0.068 -0.289 2.1 -0.35 0.068 -0.289 2.1 -0.35 0.059 -0.271 2.2 -0.35 0.005 0.026  Zeroed at 22 cm  State 2  x (cm)  y (cm)  Axial (V)  Transverse (V)  7 -0.271 7 -0.35 0.005 0.026		10	0	0.003	0.110
1       0       0.196       -0.732         1       1       -0.357       -0.484         1       1       -0.249       -0.493         1       2       -0.405       -0.195         1       3.5       -0.199       0.003         1       3       -0.296       -0.044         1       4       -0.149       0.016         1       5       -0.086       0.029         22       5       -1.002       0.023         State 1         2       -0.35       0.056       -0.253         2       -0.35       0.068       -0.289         2       -0.35       0.059       -0.271         2       -0.35       0.005       0.026         Zeroed at 22 cm       X (cm)       Y (cm)       Axial (V)       Transverse (V)         State 2       X (cm)       Y (cm)       Axial (V)       Transverse (V)		22	0	0.002	0.022
1       1       -0.357       -0.484         1       1       -0.249       -0.493         1       2       -0.405       -0.195         1       3.5       -0.199       0.003         1       3       -0.296       -0.044         1       4       -0.149       0.016         1       5       -0.086       0.029         22       5       -1.002       0.023         State 1         2.1       -0.35       0.056       -0.253         2.2       -0.35       0.068       -0.289         2.1       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       2       -0.35       0.005       0.026         State 2         x (cm)       y (cm)       Axial (V)       Transverse (V)         5.7       0.45       -0.029       -0.045	Zeroed at 22 cm				
1		1	0	0.196	-0.732
1       1       -0.249       -0.493         1       2       -0.405       -0.195         1       3.5       -0.199       0.003         1       3       -0.296       -0.044         1       4       -0.149       0.016         22       5       -1.002       0.029         22       5       -1.002       0.023         State 1         x (cm)       y (cm)       Axial (V)       Transverse (V)         2.1       -0.35       0.056       -0.253         2.2       -0.35       0.068       -0.289         2.1       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       2       -0.35       0.005       0.026         State 2       x (cm)       y (cm)       Axial (V)       Transverse (V)         5.7       0.45       -0.029       -0.045		1	1	-0.357	-0.484
1       3.5       -0.199       0.003         1       3       -0.296       -0.044         1       4       -0.149       0.016         1       5       -0.086       0.029         22       5       -1.002       0.023         State 1         2       2.1       -0.35       0.056       -0.253         2.2       -0.35       0.068       -0.289         2.1       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       State 2       Axial (V)       Transverse (V)         5.7       0.45       -0.029       -0.045		1	1	-0.249	-0.493
1       3       -0.296       -0.044         1       4       -0.149       0.016         1       5       -0.086       0.029         22       5       -1.002       0.023         State 1       x (cm)       y (cm)       Axial (V)       Transverse (V)         2.1       -0.35       0.056       -0.253         2.2       -0.35       0.068       -0.289         2.1       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       X (cm)       y (cm)       Axial (V)       Transverse (V)         5.7       0.45       -0.029       -0.045		1	2	-0.405	-0.195
1       4       -0.149       0.016         1       5       -0.086       0.029         22       5       -1.002       0.023         State 1       x (cm)       y (cm)       Axial (V)       Transverse (V)         2.1       -0.35       0.056       -0.253         2.2       -0.35       0.068       -0.289         2.1       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       State 2       Axial (V)       Transverse (V)         5.7       0.45       -0.029       -0.045		1	3.5	-0.199	0.003
State 1     5     -0.086     0.029       X (cm)     y (cm)     Axial (V)     Transverse (V)       2.1     -0.35     0.056     -0.253       2.2     -0.35     0.068     -0.289       2.1     -0.35     0.059     -0.271       22     -0.35     0.005     0.026       Zeroed at 22 cm     State 2     Axial (V)     Transverse (V)       5.7     0.45     -0.029     -0.045		1	3	-0.296	-0.044
State 1     5     -0.086     0.029       x (cm)     y (cm)     Axial (V)     Transverse (V)       2.1     -0.35     0.056     -0.253       2.2     -0.35     0.068     -0.289       2.1     -0.35     0.059     -0.271       22     -0.35     0.005     0.026       Zeroed at 22 cm     State 2     Axial (V)     Transverse (V)       5.7     0.45     -0.029     -0.045		1	4	-0.149	0.016
State 1       x (cm)       y (cm)       Axial (V)       Transverse (V)         2.1       -0.35       0.056       -0.253         2.2       -0.35       0.068       -0.289         2.1       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       State 2       Axial (V)       Transverse (V)         5.7       0.45       -0.029       -0.045		1	5	-0.086	0.029
State 1       x (cm)       y (cm)       Axial (V)       Transverse (V)         2.1       -0.35       0.056       -0.253         2.2       -0.35       0.068       -0.289         2.1       -0.35       0.059       -0.271         22       -0.35       0.005       0.026         Zeroed at 22 cm       State 2         X (cm)       y (cm)       Axial (V)       Transverse (V)         5.7       0.45       -0.029       -0.045		22	5	-1.002	
x (cm)     y (cm)     Axial (V)     Transverse (V)       2.1     -0.35     0.056     -0.253       2.2     -0.35     0.068     -0.289       2.1     -0.35     0.059     -0.271       22     -0.35     0.005     0.026       Zeroed at 22 cm     State 2     Axial (V)     Transverse (V)       5.7     0.45     -0.029     -0.045					
2.1	State 1				
2.1		x (cm)	y (cm)	Axial (V)	Transverse (V)
2.1   -0.35   0.059   -0.271				0.056	-0.253
2.1   -0.35   0.059   -0.271		2.2	-0.35	0.068	-0.289
Zeroed at 22 cm     22     -0.35     0.005     0.026       State 2     x (cm)     y (cm)     Axial (V)     Transverse (V)       5.7     0.45     -0.029     -0.045			-0.35	0.059	-0.271
State 2 x (cm) y (cm) Axial (V) Transverse (V) 5.7 0.45 -0.029 -0.045		22		0.005	0.026
x (cm) y (cm) Axial (V) Transverse (V) 5.7 0.45 -0.029 -0.045	Zeroed at 22 cm				
x (cm) y (cm) Axial (V) Transverse (V) 5.7 0.45 -0.029 -0.045					
5.7 0.45 -0.029 -0.045	State 2				
5.7 0.45 -0.029 -0.045		x (cm)	y (cm)	Axial (V)	Transverse (V)
5.7 0.045 -0.029 -0.045					-0.045
		5.7	0.045	-0.029	-0.045

## Missing Data - Temperature

 Optimally we would have spot welded a thermocouple to the bob to measure its **temperature** at the different spots. This would allow us to have a definitive number for the amount of work we have harvested from the candle.

#### Possible issues:

- The thermocouple is not without mass, this could affect how the bob interacts with the magnet, change the period, etc.
- The Thermocouple may be ferromagnetic itself and have a different curie point than that of the bob, this could alter how the magnet interacts with the bob as well.

## Thoughts – How can we benefit?

#### Hopes:

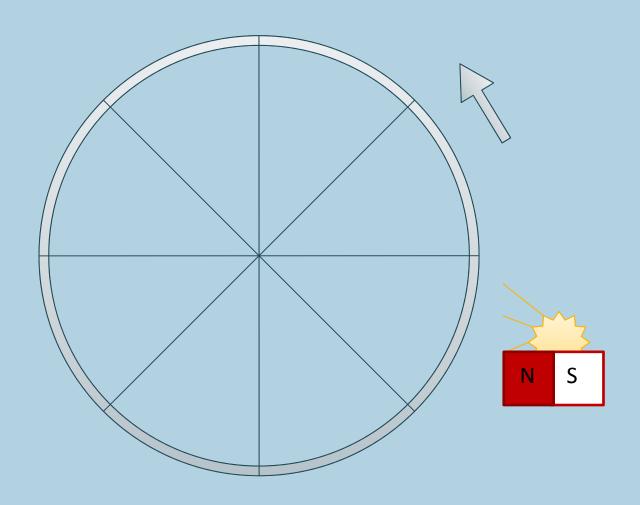
- To make a more efficient heat engine.
- Optimally we would have a ferromagnetic pendulum bob with a non-ferromagnetic, non-conducting swing rod.
- Use a Ratchet system to take energy out

#### Concerns:

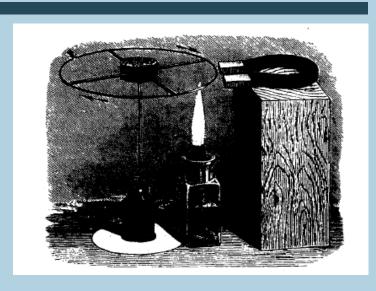
- The soot from the candle can effect the cooling and heating rate of the bob.
- The candle flame is not stable
- The current pendulum rod is both conducting and ferromagnetic.
- Due to the geometry of the bob, there are two nodes that it can stably reside in. For the most part during operation, it prefers the lower of the two, which is optimal.

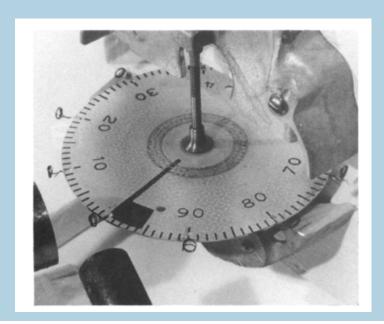
# **Possible Improvements**

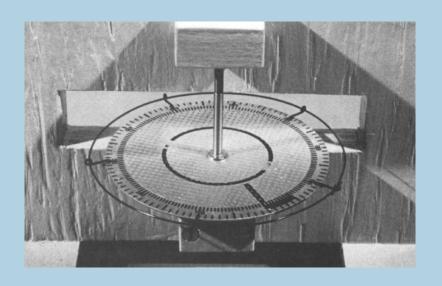
Mark III – Rotary Curie Engine



## **Examples of Rotary Type**



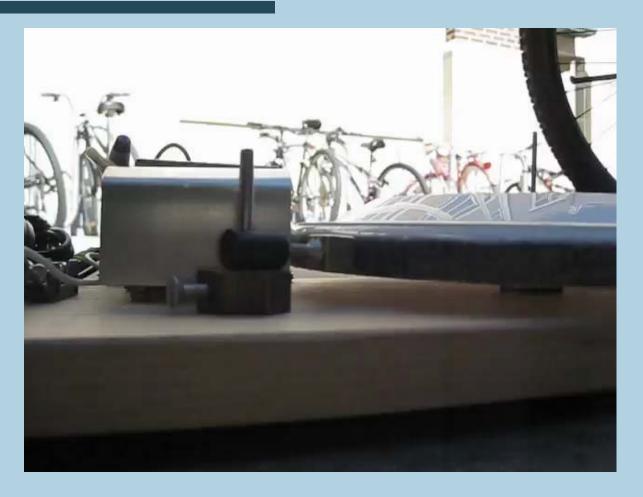




Aluminum disk with a continuous nickel loop

Aluminum disk with individual nickel loops

# **Example of Rotary Curie Engine**



The period of this engine was approximately 1 rotation every 5 seconds at an average of 16°C outside temperature. The temperature between the disk and light fluctuated between 65°C and 85°C and the temperature next to the light was about 90°C.

#### Sources:

- http://scitoys.com/scitoys/scitoys/magnets/magnets.html#curie\_effect
- http://dx.doi.org/10.1119/1.14959
- http://www.imagesco.com/articles/heatengine/HeatEngine.html
- http://www.sciencedirect.com/science/article/pii/S0143816699000378
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- http://www.doitpoms.ac.uk/tlplib/ferromagnetic/curie-weiss.php
- http://www.sciencedirect.com/science/article/pii/S0304885308011487