

Problem 5: Time Evolution (10 Points)

Consider the Hamiltonian and a second observable, B , for a system that can be represented in a 3-dimensional Hilbert space using the orthonormal basis: $|e_1\rangle$, $|e_2\rangle$ and $|e_3\rangle$

with

$$|e_1\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, |e_2\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, |e_3\rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

as:

$$H = \hbar\omega \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, B = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

The system at time $t=0$ is in the state:

$$|\Psi(0)\rangle = |e_2\rangle$$

- a) Calculate the eigenvalues and normalized eigenvectors of H and B . (2 Point)
- b) Determine $|\Psi(t)\rangle$, the wavefunction at a later time. (1 Point) *want () in e basis*
- c) Determine $P_{|\Psi(t)\rangle}(b=2)$, the probability of obtaining $b=2$ if b is measured at an arbitrary time. (1 Points)
- d) Is your probability in part c) time-dependent or time-independent? Discuss in detail. (1 Point)
- e) Derive an expression for $\frac{\partial}{\partial t}\langle B \rangle$ where $\langle B \rangle = \langle \Psi(t) | B | \Psi(t) \rangle$ by explicit differentiation using the Time-Dependent Schrodinger Equation. (2 Points) *Derive the correct theorem*
- f) Use your expression in part b) to find $\frac{\partial}{\partial t}\langle B \rangle$ for this system using the $|\Psi(t)\rangle$ you found in part a). (2 Points)
- g) Without doing further calculations describe what result you would expect for $\frac{\partial}{\partial t}\langle B \rangle$ if the initial wavefunction $|\Psi(0)\rangle = |e_2\rangle$ changes to:

$$|\Psi(0)\rangle = |e_1\rangle$$

Explain your answer in detail. (1 Point)

(a)

$$H = \hbar\omega \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\begin{vmatrix} 2\hbar\omega - \lambda & 0 & 0 \\ 0 & -\lambda & \hbar\omega \\ 0 & \hbar\omega & -\lambda \end{vmatrix} = 0$$

$$(2\hbar\omega - \lambda)(-\lambda)(-\lambda) - (\hbar\omega)(\hbar\omega)(2\hbar\omega - \lambda) = 0$$

$$(2\hbar\omega - \lambda)\lambda^2 - \hbar^2\omega^2(2\hbar\omega - \lambda) = 0$$

$$(2\hbar\omega - \lambda)(\lambda^2 - \hbar^2\omega^2) = 0$$

So letting $\lambda \rightarrow E$, our H eigenvalues are

$$\boxed{E_1 = 2\hbar\omega, E_2 = +\hbar\omega, E_3 = -\hbar\omega}$$

$|E_1 = 2\hbar\omega\rangle$

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & -2\hbar\omega & \hbar\omega \\ 0 & \hbar\omega & -2\hbar\omega \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} c_1 & \text{ can be anything} \\ -2\hbar\omega c_2 + \hbar\omega c_3 &= 0 \\ \hbar\omega c_2 - 2\hbar\omega c_3 &= 0 \end{aligned}$$

So we let $c_1 = 1$, and we must have $c_2 = c_3 = 0$. So

$$\boxed{|E_1 = 2\hbar\omega\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = |e_1\rangle}$$

(a), cont'd...

$$\underline{|E_2 = \hbar\omega\rangle}$$

$$\begin{pmatrix} \hbar\omega & 0 & 0 \\ 0 & -\hbar\omega & \hbar\omega \\ 0 & \hbar\omega & -\hbar\omega \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} \hbar\omega c_1 &= 0 \\ -\hbar\omega c_2 + \hbar\omega c_3 &= 0 \\ \hbar\omega c_2 - \hbar\omega c_3 &= 0 \end{aligned}$$

So we must have $c_1 = 0$ and $c_2 = c_3$. Let $c_2 = c_3 = 1$. Then

$$|E_2 = \hbar\omega\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} |e_2\rangle + \frac{1}{\sqrt{2}} |e_3\rangle$$

$$\underline{|E_3 = -\hbar\omega\rangle}$$

$$\begin{pmatrix} 3\hbar\omega & 0 & 0 \\ 0 & \hbar\omega & \hbar\omega \\ 0 & \hbar\omega & \hbar\omega \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} 3\hbar\omega c_1 &= 0 \\ \hbar\omega c_2 + \hbar\omega c_3 &= 0 \\ \hbar\omega c_2 + \hbar\omega c_3 &= 0 \end{aligned}$$

Then we have $c_1 = 0$ and $c_3 = -c_2$. Let $c_2 = 1$ and $c_3 = -1$. Then

$$|E_3 = -\hbar\omega\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = \frac{1}{\sqrt{2}} |e_2\rangle - \frac{1}{\sqrt{2}} |e_3\rangle.$$

(a), cont'd...

$$b = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

$$\begin{vmatrix} 1-b & 0 & -1 \\ 0 & 2-b & 0 \\ -1 & 0 & 1-b \end{vmatrix} = 0$$

$$(1-b)(2-b)(1-b) - (-1)(2-b)(-1) = 0$$

$$(2-b)(1-b)^2 - (2-b) = 0$$

$$(2-b)((1-b)^2 - 1) = 0$$

$$(2-b)(1-2b+b^2-1) = 0$$

$$(2-b)(b^2-2b) = 0$$

$$b(2-b)(b-2) = 0$$

So

$$\boxed{b_1 = 0, b_{2,3} = 2} \text{ (doubly degenerate)}$$

$$\underline{|b_1 = 0\rangle}$$

$$\begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} c_1 - c_3 &= 0 \\ 2c_2 &= 0 \\ -c_1 + c_3 &= 0 \end{aligned}$$

We must have $c_2 = 0$ and $c_1 = c_3$. Let $c_1 = c_3 = 1$. Then

$$\boxed{|b_1 = 0\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} |e_1\rangle + \frac{1}{\sqrt{2}} |e_3\rangle}$$

(a), cont'd

F2008
PROBLEM 5
PAGE 4/11

$|b_2=2\rangle$ and $|b_3=2\rangle$

We have

$$\begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & -1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{array}{l} -c_1 - c_3 = 0 \\ c_2 = \text{anything} \\ -c_1 - c_3 = 0 \end{array}$$

for both $|b_2=2\rangle$ and $|b_3=2\rangle$. Then we must have $c_3 = -c_1$,
so our generic eigenvector is

$$|b=2\rangle = \frac{1}{\sqrt{c_1^2 + c_2^2 + c_3^2}} \begin{pmatrix} c_1 \\ c_2 \\ -c_1 \end{pmatrix} = \frac{1}{\sqrt{2c_1^2 + c_2^2}} \begin{pmatrix} c_1 \\ c_2 \\ -c_1 \end{pmatrix}$$

We know that we must have $\langle b_2=2 | b_3=2 \rangle = 0$. Let
 $c_2 = 0$ and $c_1 = 1 \rightarrow c_3 = -1$ for $|b_2=2\rangle$. So

$$\boxed{|b_2=2\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \frac{1}{\sqrt{2}} |e_1\rangle - \frac{1}{\sqrt{2}} |e_3\rangle}$$

Then we want to choose c_1, c_2 , and c_3 for $|b_3=2\rangle$. So

$$\langle b_2=2 | b_3=2 \rangle = \left(\frac{1}{\sqrt{2}} \ 0 \ -\frac{1}{\sqrt{2}} \right) \begin{pmatrix} c_1 / \sqrt{2c_1^2 + c_2^2} \\ c_2 / \sqrt{2c_1^2 + c_2^2} \\ -c_1 / \sqrt{2c_1^2 + c_2^2} \end{pmatrix} = 0$$

$$\frac{c_1}{\sqrt{4c_1^2 + 2c_2^2}} + \frac{c_1}{\sqrt{4c_1^2 + 2c_2^2}} = 0$$

(a), cont'd...

Since c_2 can be anything, let $c_2 = 1$. Then

$$\frac{c_1}{\sqrt{4c_1^2 + 2}} + \frac{c_1}{\sqrt{4c_1^2 + 2}} = 0$$

The only way this works is if $c_1 = 0$. So

$$|b_3 = z\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = |e_2\rangle$$

(b)

The time evolution operator is

$$\begin{aligned} U(t, t_0) &= \sum_n |E_n\rangle \langle E_n| e^{-iE_n t/\hbar} \\ &= |E_1\rangle \langle E_1| e^{-iE_1 t/\hbar} + |E_2\rangle \langle E_2| e^{-iE_2 t/\hbar} + |E_3\rangle \langle E_3| e^{-iE_3 t/\hbar} \end{aligned}$$

So we want to determine

$$|\psi(t)\rangle = U(t, t_0) |\psi(0)\rangle.$$

We must first put our state $|\psi(0)\rangle$ into the E basis.

We know

$$|E_2 = \hbar\omega\rangle = \frac{1}{\sqrt{2}} (|e_2\rangle + |e_3\rangle)$$

$$|E_3 = -\hbar\omega\rangle = \frac{1}{\sqrt{2}} (|e_2\rangle - |e_3\rangle)$$

(b), cont'd...

Then

$$|E_2 = \hbar\omega\rangle + |E_3 = -\hbar\omega\rangle = \frac{2}{\sqrt{2}} |e_2\rangle$$

and so

$$|\psi(0)\rangle = |e_2\rangle = \frac{\sqrt{2}}{2} (|E_2\rangle + |E_3\rangle).$$

Then

$$|\psi(t)\rangle = \frac{\sqrt{2}}{2} |E_2\rangle e^{-iE_2 t/\hbar} + \frac{\sqrt{2}}{2} |E_3\rangle e^{-iE_3 t/\hbar}$$

$$|\psi(t)\rangle = \frac{\sqrt{2}}{2} \left[|E_2\rangle e^{-iE_2 t/\hbar} + |E_3\rangle e^{-iE_3 t/\hbar} \right]$$

$$= \frac{\sqrt{2}}{2} \left[\frac{1}{\sqrt{2}} (|e_2\rangle + |e_3\rangle) e^{-iE_2 t/\hbar} + \frac{1}{\sqrt{2}} (|e_2\rangle - |e_3\rangle) e^{-iE_3 t/\hbar} \right]$$

or

$$|\psi(t)\rangle = \frac{1}{2} \left[|e_2\rangle \left(e^{-iE_2 t/\hbar} + e^{-iE_3 t/\hbar} \right) + |e_3\rangle \left(e^{-iE_2 t/\hbar} - e^{-iE_3 t/\hbar} \right) \right]$$

(c)

We have

$$\begin{aligned}
\rho_{|\psi(t)\rangle}(b=2) &= |\langle b_2=2 | \psi(t) \rangle|^2 + |\langle b_3=2 | \psi(t) \rangle|^2 \\
&= \left| -\frac{1}{2\sqrt{2}} \begin{pmatrix} e^{-iE_2 t/\hbar} & e^{-iE_3 t/\hbar} \\ e & -e \end{pmatrix} \right|^2 + \left| \frac{1}{2} \begin{pmatrix} e^{-iE_2 t/\hbar} & e^{-iE_3 t/\hbar} \\ e & +e \end{pmatrix} \right|^2 \\
&= \frac{1}{8} \begin{pmatrix} iE_2 t/\hbar & iE_3 t/\hbar \\ e & -e \end{pmatrix} \begin{pmatrix} -iE_2 t/\hbar & -iE_3 t/\hbar \\ e & -e \end{pmatrix} \\
&\quad + \frac{1}{4} \begin{pmatrix} iE_2 t/\hbar & iE_3 t/\hbar \\ e & +e \end{pmatrix} \begin{pmatrix} -iE_2 t/\hbar & -iE_3 t/\hbar \\ e & +e \end{pmatrix} \\
&= \frac{1}{8} \left(1 - e^{\frac{i(E_2-E_3)t}{\hbar}} - e^{-\frac{i(E_2-E_3)t}{\hbar}} + 1 \right) \\
&\quad + \frac{1}{4} \left(1 + e^{\frac{i(E_2-E_3)t}{\hbar}} + e^{-\frac{i(E_2-E_3)t}{\hbar}} + 1 \right) \\
&= \frac{1}{8} \left(2 - 2 \cos\left(\frac{\omega t}{\hbar}\right) \right) + \frac{1}{4} \left(2 + 2 \cos\left(\frac{\omega t}{\hbar}\right) \right) \\
&= \frac{1}{4} - \frac{1}{4} \cos\left(\frac{\omega t}{\hbar}\right) + \frac{1}{2} + \frac{1}{2} \cos\left(\frac{\omega t}{\hbar}\right)
\end{aligned}$$

$$\rho_{|\psi(t)\rangle}(b=2) = \frac{3}{4} + \frac{1}{4} \cos\left(\frac{\omega t}{\hbar}\right), \quad \omega = E_2 - E_3.$$

(d)

Clearly, the probability is time-dependent. This makes sense because our wavefunction $|\psi(t)\rangle$ is a non-stationary state.

(e)

The TDSE is given by

$$i\hbar \frac{\partial}{\partial t} |\psi(t)\rangle = H |\psi(t)\rangle.$$

Taking the derivative of $\langle B \rangle$,

$$\begin{aligned} \frac{\partial}{\partial t} \langle B \rangle &= \frac{\partial}{\partial t} \langle \psi(t) | B | \psi(t) \rangle \\ &= \frac{\partial}{\partial t} \int \psi^*(t) B \psi(t) d^3x \\ &= \int \frac{\partial \psi^*(t)}{\partial t} B \psi(t) d^3x + \int \psi^*(t) \frac{\partial B}{\partial t} \psi(t) d^3x + \int \psi^*(t) B \frac{\partial \psi(t)}{\partial t} d^3x \\ &= \int \frac{\partial \psi^*(t)}{\partial t} B \psi(t) d^3x + \left\langle \frac{\partial B}{\partial t} \right\rangle + \int \psi^*(t) B \frac{\partial \psi(t)}{\partial t} d^3x \end{aligned}$$

By the TDSE,

$$\frac{\partial}{\partial t} |\psi(t)\rangle = \frac{1}{i\hbar} H |\psi(t)\rangle$$

and

$$\frac{\partial}{\partial t} \langle \psi(t) | = -\frac{1}{i\hbar} \langle \psi(t) | H$$

since $H = H^*$ because H is Hermitian.

(e), cont'd...

Then

$$\begin{aligned}\frac{\partial}{\partial t} \langle B \rangle &= \int \left(-\frac{1}{i\hbar} \psi^* H \right) B \psi d^3x + \left\langle \frac{\partial B}{\partial t} \right\rangle + \int \psi^* B \left(\frac{1}{i\hbar} H \psi \right) d^3x \\ &= -\frac{1}{i\hbar} \int \psi^* H B \psi d^3x + \left\langle \frac{\partial B}{\partial t} \right\rangle + \frac{1}{i\hbar} \int \psi^* B H \psi d^3x \\ &= \left\langle \frac{\partial B}{\partial t} \right\rangle + \frac{1}{i\hbar} \int \psi^* (HB - BH) \psi d^3x\end{aligned}$$

$$\boxed{\frac{\partial \langle B \rangle}{\partial t} = \left\langle \frac{\partial B}{\partial t} \right\rangle + \frac{1}{i\hbar} \langle [H, B] \rangle}$$

This is the generalized Ehrenfest theorem.

(f)

We know $\frac{\partial B}{\partial t} = 0$. Then

$$\begin{aligned}[H, B] &= HB - BH = \begin{pmatrix} 2\hbar\omega & 0 & 0 \\ 0 & 0 & \hbar\omega \\ 0 & \hbar\omega & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} - \\ &\quad \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2\hbar\omega & 0 & 0 \\ 0 & 0 & \hbar\omega \\ 0 & \hbar\omega & 0 \end{pmatrix} \\ &= \begin{pmatrix} 2\hbar\omega & 0 & -2\hbar\omega \\ -\hbar\omega & 0 & \hbar\omega \\ 0 & 2\hbar\omega & 0 \end{pmatrix} - \begin{pmatrix} 2\hbar\omega & -\hbar\omega & 0 \\ 0 & 0 & 2\hbar\omega \\ -2\hbar\omega & \hbar\omega & 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 & \hbar\omega & -2\hbar\omega \\ -\hbar\omega & 0 & -\hbar\omega \\ 2\hbar\omega & \hbar\omega & 0 \end{pmatrix}\end{aligned}$$

(f), cont'd...

We have

$$\langle [H, B] \rangle = \langle \psi(t) | [H, B] | \psi(t) \rangle,$$

where

$$|\psi(t)\rangle = \frac{1}{2} \left[\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \left(e^{-\frac{iE_2 t}{\hbar}} + e^{-\frac{iE_3 t}{\hbar}} \right) + \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \left(e^{-\frac{iE_2 t}{\hbar}} - e^{-\frac{iE_3 t}{\hbar}} \right) \right].$$

So

$$\begin{aligned} \langle [H, B] \rangle &= \frac{1}{2} \left[(0 \ 1 \ 0) \left(e^{\frac{iE_2 t}{\hbar}} + e^{\frac{iE_3 t}{\hbar}} \right) + (0 \ 0 \ 1) \left(e^{\frac{iE_2 t}{\hbar}} - e^{\frac{iE_3 t}{\hbar}} \right) \right] \\ &\quad \cdot \begin{pmatrix} 0 & \hbar\omega & -2\hbar\omega \\ -\hbar\omega & 0 & -\hbar\omega \\ 2\hbar\omega & \hbar\omega & 0 \end{pmatrix} \\ &\quad \cdot \frac{1}{2} \left[\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \left(e^{-\frac{iE_2 t}{\hbar}} + e^{-\frac{iE_3 t}{\hbar}} \right) + \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \left(e^{-\frac{iE_2 t}{\hbar}} - e^{-\frac{iE_3 t}{\hbar}} \right) \right] \end{aligned}$$

$$\begin{aligned} &= \frac{1}{4} \left[(0 \ 1 \ 0) \left(e^{\frac{iE_2 t}{\hbar}} + e^{\frac{iE_3 t}{\hbar}} \right) \begin{pmatrix} 0 & \hbar\omega & -2\hbar\omega \\ \hbar\omega & 0 & -\hbar\omega \\ 2\hbar\omega & \hbar\omega & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \left(e^{-\frac{iE_2 t}{\hbar}} + e^{-\frac{iE_3 t}{\hbar}} \right) \right. \\ &\quad \left. + (0 \ 1 \ 0) \left(e^{\frac{iE_2 t}{\hbar}} + e^{\frac{iE_3 t}{\hbar}} \right) \begin{pmatrix} 0 & \hbar\omega & -2\hbar\omega \\ \hbar\omega & 0 & -\hbar\omega \\ 2\hbar\omega & \hbar\omega & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \left(e^{-\frac{iE_2 t}{\hbar}} - e^{-\frac{iE_3 t}{\hbar}} \right) \right. \end{aligned}$$

$$\begin{aligned} &\quad \left. + (0 \ 0 \ 1) \left(e^{\frac{iE_2 t}{\hbar}} - e^{\frac{iE_3 t}{\hbar}} \right) \begin{pmatrix} 0 & \hbar\omega & -2\hbar\omega \\ \hbar\omega & 0 & -\hbar\omega \\ 2\hbar\omega & \hbar\omega & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \left(e^{-\frac{iE_2 t}{\hbar}} + e^{-\frac{iE_3 t}{\hbar}} \right) \right. \\ &\quad \left. + (0 \ 0 \ 1) \left(e^{\frac{iE_2 t}{\hbar}} - e^{\frac{iE_3 t}{\hbar}} \right) \begin{pmatrix} 0 & \hbar\omega & -2\hbar\omega \\ \hbar\omega & 0 & -\hbar\omega \\ 2\hbar\omega & \hbar\omega & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \left(e^{-\frac{iE_2 t}{\hbar}} - e^{-\frac{iE_3 t}{\hbar}} \right) \right] \end{aligned}$$

(f), cont'd...

F2008
PROBLEM 5
PAGE 11/11

$$= \frac{1}{4} \left[\left(2 + 2\cos\left(\frac{\omega t}{\hbar} \right) \right) (i\phi) + \left(0 + 2i\sin\left(\frac{\omega t}{\hbar} \right) \right) (-\hbar\omega) \right. \\ \left. + \left(0 + 2i\sin\left(\frac{\omega t}{\hbar} \right) \right) (\hbar\omega) + \left(2 - 2\cos\left(\frac{\omega t}{\hbar} \right) \right) (i\phi) \right]$$

$$= 0$$

So $\langle [H, B] \rangle = 0$ and $\langle \frac{\partial B}{\partial t} \rangle = 0$, and thus,

$$\boxed{\frac{\partial \langle B \rangle}{\partial t} = 0}.$$

(g) I would expect a similar result if the initial wavefunction was

$$|\psi(0)\rangle = |e_i\rangle$$

because $|\psi(t)\rangle$ would be a stationary state, since $|E_i\rangle = |e_i\rangle$.