

PROBLEM 3: Angular Momentum Operators

The eigenvector of L^2 and L_z is usually expressed as $|\ell, \ell_z\rangle = |\ell, m\rangle$. This is the ℓ_z basis with

$$L_z = \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

for $\ell = 1$.

- ~~(a)~~ Apply the raising and lowering operators and determine L_y with

$$(L_y)_{mn} = \langle \ell = 1, \ell_z = m | L_y | \ell = 1, \ell_z = n \rangle$$

in the form of a 3×3 matrix. (3 points)

- ~~(b)~~ Find the eigenvalues and normalized eigenvectors of L_y . (3 points)

- ~~(c)~~ If a particle is in the state with $\ell_z = -1$, and L_y is measured, what are the possible outcomes and their probabilities? (3 points)

- ~~(d)~~ Take the state in which $\ell_z = 1$. In this state what is the uncertainty $\Delta L_y = \langle (L_y - \langle L_y \rangle)^2 \rangle^{1/2}$? (1 points)

(a)

We know

$$L_z = \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

for $l=1$. We want to find L_y , where a given matrix element of L_y is

$$(L_y)_{mn} = \langle l=1, l_z=m | L_y | l=1, l_z=n \rangle.$$

The raising and lowering operators are, respectively,

$$L_+ = L_x + iL_y$$

$$L_- = L_x - iL_y.$$

So

$$iL_y = L_+ - L_x$$

and

$$iL_y = L_x - L_- ,$$

So

$$2iL_y = (L_+ - L_x) + (L_x - L_-)$$

$$2iL_y = L_+ - L_-$$

$$L_y = \frac{L_+ - L_-}{2i}.$$

Substituting this in for L_y in the matrix element definition,

$$(L_y)_{mn} = \langle 1, m | \frac{L_+ - L_-}{2i} | 1, n \rangle$$

(a), cont'd...

$$(L_y)_{mn} = -\frac{i}{2} [\langle l, m | L_+ | l, n \rangle - \langle l, m | L_- | l, n \rangle]$$

In general, we know

$$L_+ |l, m\rangle = \hbar \sqrt{l(l+1) - m(m+1)} |l, m+1\rangle$$

$$L_- |l, m\rangle = \hbar \sqrt{l(l+1) - m(m-1)} |l, m-1\rangle.$$

So

$$\begin{aligned} \langle l, m | L_+ | l, n \rangle &= \langle l, m | \hbar \sqrt{l(l+1) - n(n+1)} | l, n+1 \rangle \\ &= \hbar \sqrt{2 - n(n+1)} \langle l, m | l, n+1 \rangle \\ &= \hbar \sqrt{2 - n(n+1)} \delta_{m, n+1} \end{aligned}$$

and

$$\begin{aligned} \langle l, m | L_- | l, n \rangle &= \langle l, m | \hbar \sqrt{l(l+1) - n(n-1)} | l, n-1 \rangle \\ &= \hbar \sqrt{2 - n(n-1)} \langle l, m | l, n-1 \rangle \\ &= \hbar \sqrt{2 - n(n-1)} \delta_{m, n-1} \end{aligned}$$

We know

$$L_z = \hbar \begin{pmatrix} m=1 & m=0 & m=-1 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{matrix} n=1 \\ n=0 \\ n=-1 \end{matrix}$$

(a), cont'd...

Starting with $\langle 1, m | L_+ | 1, n \rangle \dots$

$$\underline{m=1}$$

$$n=1: \quad \langle 1, 1 | L_+ | 1, 1 \rangle = \hbar \sqrt{2 - (1)(1+1)} \delta_{1,2} \\ = 0$$

$$n=0: \quad \langle 1, 1 | L_+ | 1, 0 \rangle = \hbar \sqrt{2 - (0)(0+1)} \delta_{1,1} \\ = \hbar \sqrt{2}$$

$$n=-1: \quad \langle 1, 1 | L_+ | 1, -1 \rangle = \hbar \sqrt{2 - (-1)(-1+1)} \delta_{1,0} \\ = 0$$

$$\underline{m=0}$$

$$n=1: \quad \langle 1, 0 | L_+ | 1, 1 \rangle = \hbar \sqrt{2 - (1)(1+1)} \delta_{0,2} \\ = 0$$

$$n=0: \quad \langle 1, 0 | L_+ | 1, 0 \rangle = \hbar \sqrt{2} \delta_{0,1} \\ = 0$$

$$n=-1: \quad \langle 1, 0 | L_+ | 1, -1 \rangle = \hbar \sqrt{2} \delta_{0,0} \\ = \hbar \sqrt{2}$$

$$\underline{m=-1}$$

$$n=1: \quad \langle 1, -1 | L_+ | 1, 1 \rangle = 0$$

$$n=0: \quad \langle 1, -1 | L_+ | 1, 0 \rangle = \hbar \sqrt{2} \delta_{-1,1} \\ = 0$$

$$n=-1: \quad \langle 1, -1 | L_+ | 1, -1 \rangle = \hbar \sqrt{2} \delta_{-1,0} \\ = 0$$

(a), cont'd...

Thus, our matrix for L_+ is

$$L_+ = \hbar \begin{pmatrix} 0 & 0 & 0 \\ \sqrt{2} & 0 & 0 \\ 0 & \sqrt{2} & 0 \end{pmatrix} \begin{matrix} m=1 \\ m=0 \\ m=-1 \end{matrix} \begin{matrix} n=1 \\ n=0 \\ n=-1 \end{matrix}$$

For $\langle 1, m | L_- | 1, n \rangle \dots$

$m=1$

$$n=1: \langle 1, 1 | L_- | 1, 1 \rangle = \hbar \sqrt{2 - (1)(1-1)} \delta_{1,0} = 0$$

$$n=0: \langle 1, 1 | L_- | 1, 0 \rangle = \hbar \sqrt{2 - (0)(0-1)} \delta_{1,-1} = 0$$

$$n=-1: \langle 1, 1 | L_- | 1, -1 \rangle = \hbar \sqrt{2 - (-1)(-1-1)} \delta_{1,-2} = 0$$

$m=0$

$$n=1: \langle 1, 0 | L_- | 1, 1 \rangle = \hbar \sqrt{2 - (1)(1-1)} \delta_{0,0} = \hbar \sqrt{2}$$

$$n=0: \langle 1, 0 | L_- | 1, 0 \rangle = \hbar \sqrt{2 - (0)(0-1)} \delta_{0,-1} = 0$$

$$n=-1: \langle 1, 0 | L_- | 1, -1 \rangle = \hbar \sqrt{2 - (-1)(-1-1)} \delta_{0,-2} = 0$$

$m=-1$

$$n=1: \langle 1, -1 | L_- | 1, 1 \rangle = \hbar \sqrt{2} \delta_{-1,0} = 0$$

$$n=0: \langle 1, -1 | L_- | 1, 0 \rangle = \hbar \sqrt{2} \delta_{-1,-1} = \hbar \sqrt{2}$$

$$n=-1: \langle 1, -1 | L_- | 1, -1 \rangle = 0 \delta_{-1,-2} = 0$$

(a), cont'd...

F2006
PROBLEM 3
PAGE 5/11

Thus, our matrix for L_- is

$$L_- = \hbar \begin{pmatrix} 0 & \sqrt{2} & 0 \\ 0 & 0 & \sqrt{2} \\ 0 & 0 & 0 \end{pmatrix} \begin{matrix} m=1 \\ m=0 \\ m=-1 \end{matrix} \begin{matrix} n=1 \\ n=0 \\ n=-1 \end{matrix}$$

Thus, our overall matrix for L_y is

$$L_y = -\frac{i}{2} [L_+ - L_-]$$

$$= -\frac{i\hbar}{2} \left[\begin{pmatrix} 0 & 0 & 0 \\ \sqrt{2} & 0 & 0 \\ 0 & \sqrt{2} & 0 \end{pmatrix} - \begin{pmatrix} 0 & \sqrt{2} & 0 \\ 0 & 0 & \sqrt{2} \\ 0 & 0 & 0 \end{pmatrix} \right]$$

$$= -\frac{i\hbar}{2} \begin{pmatrix} 0 & -\sqrt{2} & 0 \\ \sqrt{2} & 0 & -\sqrt{2} \\ 0 & \sqrt{2} & 0 \end{pmatrix}$$

$$L_y = i\hbar \frac{\sqrt{2}}{2} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

(b)

The eigenvalues are...

$$\begin{vmatrix} -\lambda & \frac{i\hbar}{\sqrt{2}} & 0 \\ -\frac{i\hbar}{\sqrt{2}} & -\lambda & \frac{i\hbar}{\sqrt{2}} \\ 0 & -\frac{i\hbar}{\sqrt{2}} & -\lambda \end{vmatrix} = \begin{vmatrix} -\lambda & \frac{i\hbar}{\sqrt{2}} \\ -\frac{i\hbar}{\sqrt{2}} & -\lambda \end{vmatrix} = 0$$

$$(-\lambda)(-\lambda)(-\lambda) - \left(-\frac{i\hbar}{\sqrt{2}}\right)\left(\frac{i\hbar}{\sqrt{2}}\right)(-\lambda) - (-\lambda)\left(-\frac{i\hbar}{\sqrt{2}}\right)\left(\frac{i\hbar}{\sqrt{2}}\right) = 0$$

$$-\lambda^3 + \frac{\hbar^2}{2}\lambda + \frac{\hbar^2}{2}\lambda = 0$$

$$\lambda^3 - \hbar^2\lambda = 0$$

$$\lambda(\lambda^2 - \hbar^2) = 0$$

So

$$\lambda = 0, \lambda = \pm\hbar$$

or

$$\boxed{L_y = 0, \pm\hbar}$$

$$\underline{|L_y = 0\rangle}$$

$$\begin{pmatrix} 0 & \frac{i\hbar}{\sqrt{2}} & 0 \\ -\frac{i\hbar}{\sqrt{2}} & 0 & \frac{i\hbar}{\sqrt{2}} \\ 0 & -\frac{i\hbar}{\sqrt{2}} & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} 0c_1 + \frac{i\hbar}{\sqrt{2}}c_2 + 0c_3 &= 0 \\ -\frac{i\hbar}{\sqrt{2}}c_1 + 0c_2 + \frac{i\hbar}{\sqrt{2}}c_3 &= 0 \\ 0c_1 - \frac{i\hbar}{\sqrt{2}}c_2 + 0c_3 &= 0 \end{aligned}$$

We must have $c_2 = 0$. We know $c_3 = c_1$, so let $c_1 = c_3 = 1$. Then

$$\boxed{|L_y = 0\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}}$$

(b), cont'd...

$|l_y = \hbar\rangle$

$$\begin{pmatrix} -\hbar & \frac{i\hbar}{\sqrt{2}} & 0 \\ -\frac{i\hbar}{\sqrt{2}} & -\hbar & \frac{i\hbar}{\sqrt{2}} \\ 0 & -\frac{i\hbar}{\sqrt{2}} & -\hbar \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} -\hbar c_1 + \frac{i\hbar}{\sqrt{2}} c_2 + 0 c_3 &= 0 \\ -\frac{i\hbar}{\sqrt{2}} c_1 - \hbar c_2 + \frac{i\hbar}{\sqrt{2}} c_3 &= 0 \\ 0 c_1 - \frac{i\hbar}{\sqrt{2}} c_2 - \hbar c_3 &= 0 \end{aligned}$$

So $c_2 = -i\sqrt{2}c_1$, and $c_3 = -\frac{i}{\sqrt{2}}c_2$, and $c_1 - i\sqrt{2}c_2 - c_3 = 0$:

$$i\sqrt{2}c_1 + c_2 = 0$$

$$\frac{i}{\sqrt{2}}c_2 + c_3 = 0 \Rightarrow$$

$$c_1 - i\sqrt{2}c_2 - c_3 = 0$$

$$c_3 = -\frac{i}{\sqrt{2}}c_2 =$$

$$-\frac{i}{\sqrt{2}}(-i\sqrt{2}c_1)$$

$$c_3 = -c_1$$

$$|l_y = \hbar\rangle = \frac{1}{\sqrt{|c_1|^2 + |-i\sqrt{2}c_1|^2 + |-c_1|^2}} \begin{pmatrix} c_1 \\ -i\sqrt{2}c_1 \\ -c_1 \end{pmatrix}$$

Let $c_1 = 1$, then

$$|l_y = \hbar\rangle = \frac{1}{2} \begin{pmatrix} 1 \\ -i\sqrt{2} \\ -1 \end{pmatrix}$$

(b), cont'd...

$|l_y = -\hbar\rangle$

$$\begin{pmatrix} \hbar & \frac{i\hbar}{\sqrt{2}} & 0 \\ -\frac{i\hbar}{\sqrt{2}} & \hbar & \frac{i\hbar}{\sqrt{2}} \\ 0 & -\frac{i\hbar}{\sqrt{2}} & \hbar \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} \hbar c_1 + \frac{i\hbar}{\sqrt{2}} c_2 &= 0 \\ -\frac{i\hbar}{\sqrt{2}} c_1 + \hbar c_2 + \frac{i\hbar}{\sqrt{2}} c_3 &= 0 \\ -\frac{i\hbar}{\sqrt{2}} c_2 + \hbar c_3 &= 0 \end{aligned}$$

So

$$c_2 = i\sqrt{2} c_1$$

and

$$c_3 = \frac{i}{\sqrt{2}} c_2 = \frac{i}{\sqrt{2}} (i\sqrt{2} c_1) = -c_1,$$

so if $c_1 = 1 \dots$

$$\boxed{|l_y = -\hbar\rangle = \frac{1}{2} \begin{pmatrix} 1 \\ i\sqrt{2} \\ -1 \end{pmatrix}}$$

(c)

We want to determine

$$P_{|l_z = -\hbar\rangle} (l_y = 0, \hbar, \text{ and } -\hbar).$$

So

$$P_{|l_z = -\hbar\rangle} (l_y = 0) = |\langle l_y = 0 | l_z = -\hbar \rangle|.$$

But we need $|l_z = -\hbar\rangle$. So

$$\begin{pmatrix} 2\hbar & 0 & 0 \\ 0 & \hbar & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{aligned} c_1 &= 0 \\ c_2 &= 0 \\ c_3 &= 1 \end{aligned}$$

and

$$|l_z = -\hbar\rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

Then

$$P_{|l_z = -\hbar\rangle} (l_y = 0) = \left| \frac{1}{\sqrt{2}} (1 \ 0 \ 1) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right|^2 = \frac{1}{2} (1) = \frac{1}{2}$$

$$P_{|l_z = \hbar\rangle} (l_y = \hbar) = \left| \frac{1}{2} (1, i\sqrt{2}, -1) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right|^2 = \frac{1}{4} (1) = \frac{1}{4}$$

$$P_{|l_z = \hbar\rangle} (l_y = -\hbar) = \left| \frac{1}{2} (1, -i\sqrt{2}, -1) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right|^2 = \frac{1}{4} (1) = \frac{1}{4}$$

So we have a 50% chance of measuring $|l_y = 0\rangle$, and a 25% chance of measuring $|l_y = \hbar\rangle$ and $|l_y = -\hbar\rangle$, separately.

(d)

We know

$$|l_z = \hbar\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}.$$

We want to determine

$$\begin{aligned} \Delta L_y &= \left(\langle (L_y - \langle L_y \rangle)^2 \rangle \right)^{1/2} \\ &= \sqrt{\langle L_y^2 \rangle - \langle L_y \rangle^2}. \end{aligned}$$

So

$$\begin{aligned} \langle L_y \rangle &= \langle l_z = \hbar | L_y | l_z = \hbar \rangle \\ &= (1 \ 0 \ 0) \frac{i\hbar\sqrt{2}}{2} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \\ &= \frac{i\hbar\sqrt{2}}{2} (1 \ 0 \ 0) \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix} \\ &= \frac{i\hbar\sqrt{2}}{2} (0) \\ &= 0. \end{aligned}$$

We have

$$\begin{aligned} L_y^2 &= -\frac{\hbar^2}{2} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \\ &= -\frac{\hbar^2}{2} \begin{pmatrix} -1 & 0 & 1 \\ 0 & -2 & 0 \\ 1 & 0 & -1 \end{pmatrix} \end{aligned}$$

(d), cont'd...

Then

$$\begin{aligned}\langle L_y^2 \rangle &= \langle l_z = \hbar | L_y^2 | l_z = \hbar \rangle \\&= (1 \ 0 \ 0) \left(\frac{-\hbar^2}{2} \right) \begin{pmatrix} -1 & 0 & 1 \\ 0 & -2 & 0 \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \\&= \frac{-\hbar^2}{2} (1 \ 0 \ 0) \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \\&= \frac{-\hbar^2}{2} (-1) \\&= \frac{\hbar^2}{2}\end{aligned}$$

Then

$$\Delta L_y = \sqrt{\frac{\hbar^2}{2} - (0)^2}$$

$$\boxed{\Delta L_y = \frac{\hbar}{\sqrt{2}}}$$