

PHYS 3803: Quantum Mechanics I, Spring 2021

Lecture 11, March 04, 2021 (Thursday)

- Reading:
Postulates of Quantum Mechanics and Schrödinger Equation
[Griffiths 1 and 2]
- Assignment: Problem Set 5 due March 05 (Friday).
Submit your homework assignments to Canvas.

Topics for Today: Postulates of Quantum Mechanics

3.4 The Uncertainty Principle

3.5 Ehrenfest's Theorem

Topics for Next Lecture: Schrödinger Equation [Griffiths 1 and 2]

3.6 Stationary State Solutions

3.7 Schrödinger Equation

(a) Infinite Square Well

(b) Finite Square Well.

(c) The Delta-Function Potential

3.8 Equation of continuity

3.4 The Uncertainty Principle

Let A and B be two non-commuting operators with

$$[A, B] = i\hbar$$

As we have seen before, these are conjugate operators. Let ΔA be the root mean square deviation of the operator A . Thus

$$(\Delta A)^2 \equiv \langle A^2 \rangle - \langle A \rangle^2$$

Similarly let ΔB be the root mean square deviation of the operator B . Thus

$$(\Delta B)^2 = \langle B^2 \rangle - \langle B \rangle^2$$

then

$$\Delta A \Delta B \geq \frac{\hbar}{2} \quad (\text{Heisenberg's uncertainty principle})$$

First of all notice that

$$\begin{aligned}(\Delta\Omega)^2 &= \langle\Omega^2\rangle - \langle\Omega\rangle^2 \\&= \langle\Omega^2 - 2\Omega\langle\Omega\rangle + \langle\Omega\rangle^2\rangle \\&= \langle(\Omega - \langle\Omega\rangle)^2\rangle \\ \Delta\Omega &\equiv \langle(\Omega - \langle\Omega\rangle)^2\rangle^{1/2} = [\langle\Omega^2\rangle - \langle\Omega\rangle^2]^{1/2}\end{aligned}$$

where (i) $\Delta\Omega$ is the standard deviation which measures the average fluctuation around the mean.

N.B. (i) $\Delta\Omega$ is often called the root mean squared deviation or the uncertainty in Ω .

(ii) $(\Delta\Omega)^2$ is called the mean square deviation or the variance.

Let us define

$$\delta A \equiv A - \langle A \rangle \quad \text{and} \quad \delta B \equiv B - \langle B \rangle.$$

Then we have $[\delta A, \delta B] = [A, B] = i\hbar$. Furthermore,

$$\begin{aligned} (\Delta A)^2 (\Delta B)^2 &= \langle (A - \langle A \rangle)^2 \rangle \langle (B - \langle B \rangle)^2 \rangle \\ &= \langle (\delta A)^2 \rangle \langle (\delta B)^2 \rangle \\ &\geq |\langle \delta A \delta B \rangle|^2 \quad (\text{Schwartz inequality}) \\ &= \left| \left\langle \frac{1}{2} (\delta A \delta B + \delta B \delta A) + \frac{1}{2} (\delta A \delta B - \delta B \delta A) \right\rangle \right|^2 \\ &= \left| \left\langle \frac{1}{2} (\delta A \delta B + \delta B \delta A) + \frac{1}{2} [\delta A, \delta B] \right\rangle \right|^2 \\ &= \left| \left\langle \frac{1}{2} (\delta A \delta B + \delta B \delta A) + \frac{1}{2} (i\hbar) \right\rangle \right|^2 \quad (\text{complex } z = x + iy) \\ &= \left| \left\langle \frac{1}{2} (\delta A \delta B + \delta B \delta A) \right\rangle \right|^2 + \frac{\hbar^2}{4} \quad (|z|^2 = x^2 + y^2). \end{aligned}$$

Therefore,

$$\Delta A \Delta B \geq \frac{\hbar}{2}.$$

- This tells us that for any two conjugate variables, there is a minimum of uncertainty associated with their measurements.
- Note that the Schwartz inequality becomes an equality if the vectors are parallel to each other. Thus

$$\delta A|\psi\rangle = \lambda\delta B|\psi\rangle$$

and

$$\begin{aligned}\frac{1}{2}\langle\psi|(\delta A\delta B + \delta B\delta A)|\psi\rangle &= \frac{1}{2}\langle\psi|\lambda^*\delta B\delta B + \lambda\delta B\delta B)|\psi\rangle \\ &= \frac{1}{2}(\lambda^* + \lambda)\langle\psi|\delta B\delta B|\psi\rangle \\ &= \frac{1}{2}(\lambda^* + \lambda)\langle\delta B\psi|\delta B\psi\rangle.\end{aligned}$$

If this vanishes, then we have

$$(\Delta A)(\Delta B) = \frac{\hbar}{2}$$

which is the minimum uncertainty.

Now we have

$$\frac{1}{2}\langle\psi|(\delta A\delta B + \delta B\delta A)|\psi\rangle = 0 \quad \text{if} \quad \frac{1}{2}(\lambda^* + \lambda)\langle\delta B\psi|\delta B\psi\rangle = 0.$$

Since $\langle\delta B\psi|\delta B\psi\rangle$ is greater than zero unless $|\delta B\psi\rangle = 0$, then

$$\lambda^* + \lambda = 0 \quad \text{or} \quad \lambda^* = -\lambda.$$

Thus λ is pure imaginary.

Let $\lambda = -ic$ where c is real. Then we have

$$\delta A|\psi\rangle = \lambda\delta B|\psi\rangle = -ic\delta B|\psi\rangle.$$

N.B. $\langle\Omega\rangle = \langle\psi|\Omega|\psi\rangle$ and $|\Omega\psi\rangle \equiv \Omega|\psi\rangle$.

Furthermore, we know that

$$\delta A = A - \langle A \rangle \quad \text{and} \quad \delta B = B - \langle B \rangle.$$

Since A and B are conjugate operators, we can express them as differential operators. For example

$$\langle x|P|y\rangle = -i\hbar \frac{d}{dx} \delta(x-y) \text{ (x basis)} \quad \text{and} \quad \langle p|X|q\rangle = i\hbar \frac{d}{dp} \delta(p-q) \text{ (p basis)}.$$

In the x basis, let us consider

$$A = X, \quad B = P \rightarrow -i\hbar \frac{d}{dx}, \quad \text{and} \quad \delta X|\psi\rangle = \lambda \delta P|\psi\rangle = -ic\delta P|\psi\rangle.$$

Then we have

$$(x - \langle X \rangle) \psi(x) = -ic \left(-i\hbar \frac{d}{dx} - \langle P \rangle \right) \psi(x)$$

or

$$\frac{d\psi}{dx} = -\frac{1}{c\hbar} (x - \langle X \rangle - ic\langle P \rangle) \psi(x)$$

and then

$$\psi(x) = N \exp \left[-\frac{1}{2c\hbar} (x - \langle X \rangle)^2 + \frac{i}{\hbar} \langle P \rangle x \right] .$$

This is a Gaussian centered at $x = \langle X \rangle$ with a width Δx given by

$$\frac{1}{(\Delta x)^2} = \frac{1}{c\hbar}$$

where N is the normalization constant.

Exercise: Find the normalization constant for

$$\psi(x) = N \exp \left[-\frac{1}{2c\hbar} (x - \langle X \rangle)^2 + \frac{i}{\hbar} \langle P \rangle x \right]$$

such that

$$\int |\psi(x)|^2 dx = 1.$$

3.5 Ehrenfest's Theorem

Let us consider an operator Ω and its expectation value $\langle \Omega \rangle \equiv \langle \psi | \Omega | \psi \rangle$ in a state with state vector $|\psi\rangle$.

We are interested in the change of $\langle \Omega \rangle$ in time

$$\begin{aligned} \frac{d}{dt} \langle \Omega \rangle &= \frac{d}{dt} \langle \psi | \Omega | \psi \rangle \\ &= \langle \dot{\psi} | \Omega | \psi \rangle + \langle \psi | \frac{\partial}{\partial t} \Omega | \psi \rangle + \langle \psi | \Omega | \dot{\psi} \rangle . \end{aligned}$$

We know from Schrödinger equation that

$$\begin{aligned} i\hbar \frac{d}{dt} |\psi\rangle &= i\hbar |\dot{\psi}\rangle = H |\psi\rangle \\ -i\hbar \langle \dot{\psi} | &= \langle \psi | H . \end{aligned}$$

N.B. The Hamiltonian is Hermitian $H^\dagger = H$.

Substituting this into the above equation we have

$$\begin{aligned}\frac{d}{dt}\langle\Omega\rangle &= \langle\dot{\psi}|\Omega|\psi\rangle + \langle\psi|\frac{\partial}{\partial t}\Omega|\psi\rangle + \langle\psi|\Omega|\dot{\psi}\rangle \\ &= \frac{i}{\hbar}\langle\psi|H\Omega|\psi\rangle + \langle\psi|\frac{\partial}{\partial t}\Omega|\psi\rangle - \frac{i}{\hbar}\langle\psi|\Omega H|\psi\rangle \\ &= \langle\psi|\frac{\partial}{\partial t}\Omega|\psi\rangle - \frac{i}{\hbar}\langle\psi|[\Omega, H]|\psi\rangle.\end{aligned}$$

If the operator Ω has no explicit time dependence, then we can write

$$\frac{d}{dt}\langle\Omega\rangle = -\frac{i}{\hbar}\langle\psi|[\Omega, H]|\psi\rangle \quad \text{or} \quad i\hbar\frac{d}{dt}\langle\Omega\rangle = \langle\psi|[\Omega, H]|\psi\rangle.$$

This is known as Ehrenfest's Theorem.

We now have

$$\frac{d\Omega}{dt} = -\frac{i}{\hbar}[\Omega, H] \quad \text{similar to} \quad \frac{d\omega}{dt} = \{\omega, H\}$$

which is Hamilton's equation of motion.

The quantum correspondence principle is expressed as

$$[\Omega_1, \Omega_2] = i\hbar\{\omega_1, \omega_2\} = i\hbar \sum_i \left(\frac{\partial \omega_1}{\partial x_i} \frac{\partial \omega_2}{\partial p_i} - \frac{\partial \omega_1}{\partial p_i} \frac{\partial \omega_2}{\partial x_i} \right) .$$

We can consider

$$\langle [\Omega, H] \rangle = i\hbar \langle \{\omega, H\} \rangle = i\hbar \frac{d}{dt} \langle \omega \rangle = i\hbar \frac{d}{dt} \langle \Omega \rangle$$

that is

$$i\hbar \frac{d}{dt} \langle \Omega \rangle = \langle [\Omega, H] \rangle .$$

Example:

Let us consider the motion of one particle with

$$H = \frac{P^2}{2m} + V(X) \rightarrow H = \frac{-\hbar^2}{2m} \frac{d^2}{dx^2} + V(x).$$

We can investigate

$$\begin{aligned} \frac{d\langle X \rangle}{dt} &= \frac{d}{dt} \langle \psi | X | \psi \rangle \\ &= -\frac{i}{\hbar} \langle \psi | [X, H] | \psi \rangle \\ &= -\frac{i}{\hbar} \langle \psi | [X, \frac{P^2}{2m} + V(x)] | \psi \rangle \\ &= -\frac{i}{\hbar} \langle \psi | [X, \frac{P^2}{2m}] | \psi \rangle \\ &= -\frac{i}{\hbar} \frac{1}{2m} \langle \psi | P[X, P] + [X, P]P | \psi \rangle \\ &= -\frac{i}{\hbar} \frac{1}{2m} (2i\hbar) \langle \psi | P | \psi \rangle = \frac{1}{m} \langle \psi | P | \psi \rangle. \end{aligned}$$

We have found

$$\frac{d}{dt}\langle X \rangle = -\frac{i}{\hbar}\langle \psi|[X, H]|\psi \rangle = \frac{\langle P \rangle}{m}.$$

In classical mechanics, we know that

$$\dot{x} = \frac{\partial H}{\partial p} = \frac{p}{m}, \quad \text{and} \quad \dot{p} = -\frac{\partial H}{\partial x} = -\frac{d}{dx}V(x).$$

Thus we have seen that for an operator Ω , the expectation value $\langle \Omega \rangle$ has the following evolution equation

$$\frac{d}{dt}\langle \Omega \rangle = -\frac{i}{\hbar}\langle [\Omega, H] \rangle$$

or

$$i\hbar \frac{d}{dt}\langle \Omega \rangle = \langle [\Omega, H] \rangle.$$

That means the expectation value of an operator $\langle \Omega \rangle$ follows the classical equation of motion.

Let us consider a system with the state vector $|\psi\rangle$.

- The position measurement yields a value x with uncertainty ΔX .
- And the momentum measurement yields a value p with uncertainty

$$\Delta P \simeq \frac{\hbar}{2\Delta X}.$$

Note that the uncertainty relation for X and P is

$$\Delta X \Delta P \geq \frac{\hbar}{2}.$$

If the state is such that the uncertainties ΔX and ΔP are negligible compared to the measured values x and p then we replace

$$\langle X \rangle = x \quad \text{and} \quad \langle P \rangle = p$$

where x and p are classical quantities.

For such a state, therefore, the fluctuation around the mean is negligible and we can write

$$\langle \Omega(X, P) \rangle = \Omega(\langle X \rangle, \langle P \rangle) = \Omega(x, p) = \omega(x, p)$$

Therefore in such a case we can write the Ehrenfest equation as

$$\frac{d}{dt} \langle \Omega \rangle = \frac{d\omega}{dt} = \{\omega, H\}$$

which is Hamilton's equation.

Thus we see that quantum mechanics reduces to classical Hamiltonian mechanics when it is applied to macroscopic systems.