PHYS 3803: Quantum Mechanics I, Spring 2021 Lecture 7, February 18, 2021 (Thursday)

- Handout: Solutions to Problem Set 2.
- Reading: Mathematical Tools (Chapter 3 in Griffiths)
- Assignment: Problem Set 4 due February 26 (Friday). Submit your homework assignments to Canvas.

Topics for Today: Mathematical Tools

- 2.6 Expectation Value
- $2.7\,$ Representations of Dirac Delta Function
- 2.8 Operators in Infinite Dimensions

Topics for Next Lecture: Mathematical Tools

- 2.9 Hilbert Space and Fourier Transform
- 2.10 The Momentum Space or the p-basis
- 2.11 The Uncertainty Principle

2.6 Expectation Value

Let us consider a physics system described by a state vector $|\psi\rangle$.

• The outcome of a measurement corresponding to operator Ω is an eigenvalue ω_i with probability $P(\omega_i)$

$$P(\omega_i) = \frac{|\langle \omega_i | \psi \rangle|^2}{\langle \psi | \psi \rangle} \,.$$

- Now suppose an infinite number of such experiments are performed. Then we obtain a variety of values with different probabilities.
- The statistical mean of this measurement is and define an average of the operator to be

$$\langle \Omega
angle = \sum_i P(\omega_i) \omega_i \,.$$

Clearly, therefore,

$$\begin{split} \langle \Omega \rangle &= \sum_{i} P(\omega_{i})\omega_{i} \\ &= \sum_{i} |\langle \omega_{i} | \psi \rangle|^{2} \omega_{i} \quad (|z|^{2} = z^{*}z) \\ &= \sum_{i} \langle \psi | \omega_{i} \rangle \langle \omega_{i} | \psi \rangle \omega_{i} \quad (\langle \psi | \omega_{i} \rangle = \langle \omega_{i} | \psi \rangle^{*}) \\ &= \sum_{i} \langle \psi | \Omega | \omega_{i} \rangle \langle \omega_{i} | \psi \rangle \quad \text{(eigenvalue equation)} \\ &= \langle \psi | \Omega | \left(\sum_{i} |\omega_{i} \rangle \langle \omega_{i} | \right) | \psi \rangle \\ &= \langle \psi | \Omega | \psi \rangle \quad \text{with} \quad \sum_{i} |\omega_{i} \rangle \langle \omega_{i} | = \mathbf{I} \end{split}$$

where we have applied the completeness relation and have assumed that the state vector $|\psi\rangle$ is normalized.

This is the **expectation value** of the operator Ω in the state $|\psi\rangle$.

In the coordinate space, the state vector becomes a wave function $\psi(x)$

$$\psi(x) \equiv \langle x | \psi \rangle$$
 (similar to $v_i = \langle e_i | v \rangle$)

that is the inner product of $|\psi\rangle$ with the normalized basis vector $|x\rangle$. The vectors $|x\rangle$ and $|y\rangle$ form a complete set of orthonormal basis

 $\langle x|y\rangle = \delta(x-y)$ (orthonormal relation) $\langle e_i|e_j\rangle = \delta_{ij}$ $\int |x\rangle\langle x|\,dx = I$ (completeness relation) $\sum_i |e_i\rangle\langle e_i| = I.$

And the expectation value of Ω becomes

$$egin{aligned} &\langle\psi|\left(\int|x
angle\langle x|\,dx
ight)|\Omega|\left(\int|y
angle|\langle y|\,dy
ight)|\psi
ight
angle\ &=&\int dx\,\int dy\,\delta(x-y)\,\langle\psi|x
angle\langle x|\Omega|y
angle\langle y|\psi
angle\ &=&\int\psi^*(x)\langle x|\Omega|x
angle\psi(x)\,dx\,. \end{aligned}$$

In the same way, we can define the expectation value of the operator Ω^2 in the state $|\psi\rangle$. Thus

$$\begin{split} \langle \Omega^2 \rangle &= \langle \psi | \Omega^2 | \psi \rangle \\ &= \langle \psi | \Omega^2 (\sum_i |\omega_i \rangle \langle \omega_i |) | \psi \rangle \\ &= \sum_i \langle \psi | \Omega^2 | \omega_i \rangle \langle \omega_i | \psi \rangle \\ &= \sum_i \langle \psi | \Omega | \omega_i \rangle \langle \omega_i | \psi \rangle \omega_i \\ &= \sum_i \langle \psi | \omega_i \rangle \langle \omega_i | \psi \rangle \omega_i^2 \\ &= \sum_i P(\omega_i) \omega_i^2 \end{split}$$

Thus these are like the familiar quantities in statistical mechanics.

Wave Function and Matrix Elements

In the Hilbert space, a physics system is described with a state vector $|\psi\rangle$ and an observable ω becomes a quantum operator Ω .

In the coordinate space with x-basis, the eigenvalue equation is

 $|X|x\rangle = x|x\rangle$ or $|X|y\rangle = y|y\rangle$

with the orthonormal relation $\langle x|y\rangle = \delta(x-y)$.

The state vector becomes a wave function

 $\psi(x) \equiv \langle x | \psi \rangle$

and the operator is represented by a matrix element

 $\langle x|\Omega|y\rangle$.

What are $\langle x|X|y\rangle$ and $\langle x|P|y\rangle$ in the x-basis?

In the x-basis, the matrix element for the operator X becomes

$$\langle x|X|y\rangle = y\langle x|y\rangle = y\delta(x-y)$$
 or
 $\langle x|X|y\rangle = x\langle x|y\rangle = x\delta(x-y)$ (eigenvalue equations)

The operator P is the conjugate momentum w.r.t. X, such that $[X,P] \equiv XP - PX = i\hbar \quad (\text{commutation relation})$

and

$$\Delta X \Delta P \geq \frac{\hbar}{2}$$
(uncertainty relation).

In the x-basis, the matrix element of P becomes

$$\langle x|P|y\rangle = -i\hbar \frac{d}{dx}\delta(x-y).$$

In the p-basis, the eigenvalue equations are

with the orthonormal relation $\langle p|q\rangle = \delta(p-q)$.

The state vector becomes a wave function

 $\phi(p) \equiv \langle p | \psi \rangle$

and an operator Ω is represented by a matrix element

 $\langle p|\Omega|q
angle$.

The matrix elements for P and X in the p-basis become

- for $\Omega = P$, $\langle p|P|q \rangle = q\delta(p-q) = p\delta(p-q)$ (eigenvalue equations),
- for $\Omega = X$,

$$\langle p|X|q\rangle = i\hbar \frac{d}{dp}\delta(p-q).$$

Example 1: $\Omega = X$

In the coordinate space with x-basis, let us choose the normalized eigenvectors as $|x\rangle$ and $|y\rangle$ that are eigenvectors of the operator X or \hat{X} . The state vector becomes a wave function $\psi(x)$

 $\psi(x) \equiv \langle x | \psi \rangle$ or $\psi(y) \equiv \langle y | \psi \rangle$.

The eigenvalue equation for the operator X is

 $X|x\rangle = x|x\rangle$ or $X|y\rangle = y|y\rangle$.

The normalized eigenvectors from a complete set of orthonormal basis.

- What is the orthonormal relation for $|x\rangle$ and $|y\rangle$?
- What is the completeness relation for $|x\rangle$ or $|y\rangle$?

Applying the eigenvalue equation $X|x\rangle = x|x\rangle$ or $X|y\rangle = y|y\rangle$, the completenes relations of basis vectors $|x\rangle$ and $|y\rangle$

$$\int |x\rangle \langle x| \, dx = I$$
 and $\int |y\rangle \langle y| \, dy = I$,

and the orthonormal relation

$$\langle x|y\rangle = \delta(x-y)$$

we obtain the expectation value of X

$$\begin{aligned} \langle \psi | X | \psi \rangle &= \langle \psi | \mathbf{I} | X | \mathbf{I} | \psi \rangle = \langle \psi | \left(\int x \rangle \langle x | dx \right) | X | \left(\int |y \rangle | \langle y | dy \right) | \psi \rangle \\ &= \int dx \int dy \, \langle \psi | x \rangle \langle x | X | y \rangle \langle y | \psi \rangle \text{ with } \langle x | X | y \rangle = y \delta(x - y) \\ &= \int dx \int dy \, \psi^*(x) \left[y \delta(y - x) \right] \psi(y) \text{ with } \langle \psi | x \rangle = \psi^*(x) \\ &= \int \psi^*(x) \left[x \, \psi(x) \right] dx \,. \end{aligned}$$

Example 2: $\Omega = P$

In the momentum space with p-basis, let us choose the normalized eigenvectors as $|p\rangle$ and $|q\rangle$ that are eigenvectors of the operator P or \hat{P} . The state vector $\psi\rangle$ becomes a wave function $\phi(p)$

$$\phi(p) \equiv \langle p | \psi \rangle \quad \text{or} \quad \phi(q) \equiv \langle q | \psi \rangle.$$

The eigenvalue equation for the operator P is

$$P|p\rangle = p|p\rangle$$
 or $P|q\rangle = q|q\rangle$.

The normalized eigenvectors from a complete set of orthonormal basis with the completeness relation

$$\int |p\rangle \langle p| dp = I$$
 and $\int |q\rangle \langle q| dq = I$,

as well as the orthonormal relation

$$\langle p|q\rangle = \delta(p-q).$$

In the x-basis, let us apply the completeness relation

$$\int |x\rangle \langle x| \, dx = I \quad \text{or} \quad \int |y\rangle \langle y| \, dy = I$$

and the matirx element of ${\cal P}$

$$\langle x|P|y\rangle = -i\hbar \frac{d}{dx}\delta(x-y).$$

The expectation value of P becomes

$$\begin{aligned} \langle \psi | P | \psi \rangle &= \langle \psi | \mathbf{I} | P | \mathbf{I} | \psi \rangle = \langle \psi | \left(\int x \rangle \langle x | dx \right) | P | \left(\int |y \rangle | \langle y | dy \right) | \psi \rangle \\ &= \int dx \int dy \, \langle \psi | x \rangle \langle x | P | y \rangle \langle y | \psi \rangle \\ &= \int dx \int dy \, \psi^*(x) \left[-i\hbar \frac{d}{dx} \delta(x-y) \right] \psi(y) \\ &= -i\hbar \int \psi^*(x) \left[\frac{d}{dx} \psi(x) \right] dx \,. \end{aligned}$$

2.7 Representations of Dirac Delta Function

Infinite Dimensional Vector Spaces

Let us consider a string fixed at two end points: x = 0 and x = L. In the limit with N discrete points and N-1 equal intervals, we can think of an ordered N-tuple describing the displacement at these N points. Let us denote that by $f_N(x_i)$. This, of course, will not be the true displacement f(x), but as N is made larger and larger, would become closer to the true description. We can consider the ordered N-tuple, $f_N(x_1), f_N(x_2), \dots, f_N(x_N)$ to be an N-dimensional vector denoted by

$$|f_N\rangle = \begin{pmatrix} f_N(x_1) \\ f_N(x_2) \\ \vdots \\ f_N(x_N) \end{pmatrix} = \sum_{i=1}^N f_N(x_i) |x_i\rangle$$

in terms of the basis vectors

where 1 appears only at the *i*-th place and $f_N(x_i) = \langle x_i | f_N \rangle$.

The vectors $|x_i\rangle$ form a set of complete and orthonormal basis vectors

$$\langle x_i | x_j \rangle = \delta_{ij},$$

 $\sum_{i=1}^N |x_i \rangle \langle x_i | = I = I dentity operator.$

Let us consider the limit $N \to \infty$ with the length of each interval becoming infinitesimal such that the positions become continuous variables and the displacement $f_{\infty}(x)$ approaches the true displacement. We can pass from finite dimensions to infinite dimensions by making $N \to \infty$

$$\langle f_N | g_N \rangle = \sum_{i,j=1}^N \langle x_j | f_N^*(x_j) g_N(x_i) | x_i \rangle$$

$$= \sum_{i,j=1}^N f_N^*(x_j) g_N(x_i) \langle x_j | x_i \rangle$$

$$= \sum_{i,j=1}^N f_N^*(x_i) g_N(x_j) \delta_{ij}$$

$$= \sum_i^N f_N^*(x_i) g_N(x_i).$$

And in particular

$$\langle f_N | f_N \rangle = \sum_i^N f_N(x_i) f_N^*(x_i) = \sum_i^N |f_N(x_i)|^2.$$

This diverges as $N \to \infty$. Therefore, we need a redefinition of the inner product such that a finite limit is obtained as $N \to \infty$. This can be done by defining

$$\langle f_N | g_N \rangle \equiv \sum_i^N f_N^*(x_i) g_N^*(x_i) (\frac{L}{N-1})$$

 $\rightarrow \int_0^L f_N^*(x) g_N(x) dx, \text{ as } N \to \infty.$

Thus for vectors defined within the interval $a \leq x \leq b$, we have

$$\langle f_N | g_N \rangle \rightarrow \int_a^b f_N^*(x) g_N(x) dx = \int_a^b f^*(x) g(x) dx \text{ as } N \to \infty.$$

The completeness relation still holds,

$$\int_{a}^{b} |x\rangle \langle x| dx = I = \text{the identity operator.}$$

Multiplying the above equation on the left by $\langle y |$ and on the right by $|f\rangle$, we obtain

$$\int_{a}^{b} \langle y|x \rangle \langle x|f \rangle dx = \langle y|f \rangle, \text{ or}$$
$$\int_{a}^{b} \langle y|x \rangle f(x) dx = f(y)$$

From the orthogonality relation, we know that

$$\langle y|x\rangle = 0$$
, if $y \neq x$.

Therefore, we can limit the range of integration to an infinitesimal region

$$\int_{x_0-\epsilon}^{x_0+\epsilon} f(x) \langle x | x_0 \rangle dx = f(x_0).$$

If $\langle x|x_0 \rangle$ is finite at $x = x_0$, then the left hand side would vanish. Let us denote

$$\langle x|y\rangle = \delta(x-y)$$
.

- Thus $\delta(x-y) = 0$ if $x \neq y$.
- For x = y it diverges in such a way that the integral is unity:

$$\int f(x)\delta(x-y)dx = f(y), \text{ and } \int \delta(x-y)dx = 1, \text{ with } f(x) = 1.$$

This is called the Dirac delta function and it is used to normalize continuous basis vectors

$$\langle x|y\rangle = \delta(x-y)$$
.

Properties of the Dirac delta function:

(i)
$$\int \delta(x-y)f(x)dx = f(y)$$
.
(ii) $\delta(x-y) = \langle x|y \rangle = \langle x|y \rangle^{\dagger} = \langle y|x \rangle = \delta(y-x)$. It is an even function.
(iii) $\int \delta'(x-y)f(x)dx = -f'(y)$.
Proof:

$$\begin{aligned} \int \left[\frac{d}{dx}\delta(x-y)\right]f(x)dx &= \int_a^b \left\{\frac{d}{dx}\left[\delta(x-y)f(x)\right] - \delta(x-y)\frac{d}{dx}f(x)\right\} \\ &= \delta(x-y)f(x)|_a^b - \int_a^b \delta(x-y)\frac{d}{dx}f(x)\,dx \\ &= -\frac{d}{dx}f(x)|_{x=y} = -f'(y)\,. \end{aligned}$$

It is clear that

$$\frac{d}{dx}\delta(x-y) = -\frac{d}{dy}\delta(x-y)\,.$$

More general properties:

$$\delta'(x) = -\delta'(-x)$$

$$x\delta(x) = 0$$

$$x\delta'(x) = -\delta(-x)$$

$$\delta(ax) = \frac{1}{|a|}\delta(x)$$

$$\delta(x^2 - a^2) = \frac{1}{2a}[\delta(x - a) + \delta(x + a)] \quad \text{for} a > 0$$

$$f(x)\delta(x - a) = f(a)\delta(x - a)$$

$$\int \delta(x - a)\delta(x - b)dx = \delta(a - b)$$

One more very useful property:

$$\delta(f(x)) = \sum_{i} \frac{\delta(x - x_i)}{|df(x)/dx_i|}|_{x = x_i}$$

where x_i is chosen so that $f(x_i) = 0$, i.e. the roots of $f(x_i) = 0$.

Gaussian Representation of the Dirac delta function

In quantum mechanics, we often express the Dirac delta function as an integral

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ik(x-x_0)} dk = \delta(x-x_0)$$

or

$$\int_{-\infty}^{\infty} e^{ik(x-x_0)} dk = 2\pi\delta(x-x_0)$$

This is known as the Gaussian Representations of the Dirac delta function.

Let us consider

$$I = \int_{-\epsilon}^{\epsilon} f(x) \lim_{q \to \infty} \frac{1}{2\pi} \int_{-q}^{q} e^{ikx} dk = \lim_{q \to \infty} \frac{1}{2\pi} \int_{-\epsilon}^{\epsilon} f(x) \frac{2\sin qx}{x}$$
$$= \lim_{q \to \infty} \frac{1}{\pi} Im \left[\int_{-\epsilon}^{\epsilon} f(x) \frac{e^{iqx}}{x} \right]$$

Let z = qx, then

$$z = -\epsilon \rightarrow z = -q\epsilon$$
$$z = \epsilon \rightarrow z = q\epsilon$$

Therefore, the integral becomes

$$I = \lim_{q \to \infty} Im \left[\int_{-q\epsilon}^{q\epsilon} f(z/q) \frac{e^{iz}}{z} \right]$$

In the limit of $q \to \infty$, we can use contour integral. There is a pole at z = 0. Therefore, the value of the integral is

$$I = Im[\frac{1}{\pi} \cdot i\pi f(0)] = f(0)$$

Thus

$$\int_{-\epsilon}^{\epsilon} f(x) \lim_{q \to \infty} \frac{1}{2\pi} \int_{-q}^{q} e^{ikx} dk = f(0),$$
$$\implies \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} dk = \delta(x).$$