

Read 8.4 - 8.5

Exam Monday 7:30 A.M. HERE  
Chapters 6, 7

Equation sheet online  
(nearly written)

Old exam questions on the

chapter 6 test Questions  
(Fixed some errors in answers)  
If find others, let me know

Group discussion Q&A

# chapter 8

## Rotational Motion

Bring all of the ideas we have learned in previous 7 chapters together and apply them to rotational motion

Kinematic Equations

Forces

Energy

Momentum

These concepts modified to deal with rotations

Apply "old" ideas to "new" problems

## Some Definitions

Rigid Body: An object that has a definite unchanging shape

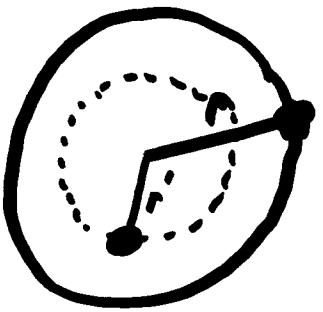
Fixed axis of rotation: A single non-changing axis around which the object rotates

Translational motion: movement of an object through space without rotation

Rotational motion: motion around an axis of rotation

can have both translational and rotational motion at the same time

# First Look at spinning wheel 1



$$V = \frac{\text{Distance}}{\text{time}} \quad r' = \frac{r}{2}$$

$$V_{\text{red}} = \frac{2\pi r}{t}$$

$$V_{\text{blue}} = \frac{2\pi r'}{t}$$

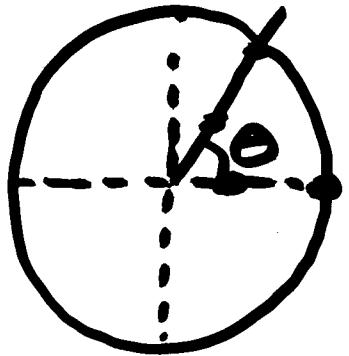
$$\frac{V_{\text{red}}}{V_{\text{blue}}} = \frac{2\pi r/t}{2\pi r'/t} = \frac{r}{r'}$$

$$= 2$$

red traveling twice as fast as  
blue

so 2 objects spinning at different distances from center have different velocities

what is constant for both objects?



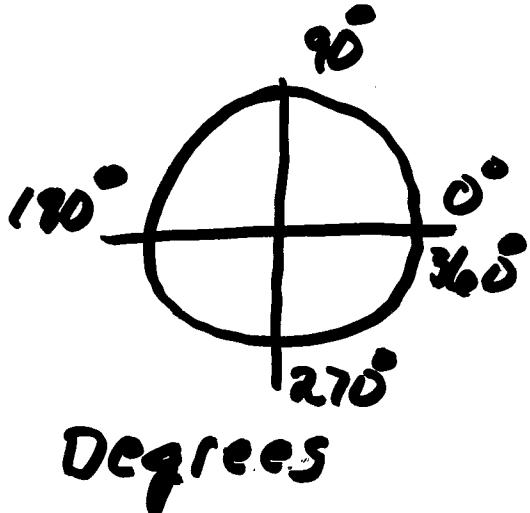
Have same change in angle

$$\text{velocity} = \frac{\Delta x}{\Delta t}$$

$$\text{angular velocity} = \frac{\Delta \theta}{\Delta t} = \omega \text{ (omega)}$$

\* Greek letters often used for angular quantities

# How to define $\Theta$ ?



↙ Degrees is a unit  
 $360^\circ$  in a circle

## Radians

$$\Theta = \frac{s}{r}$$

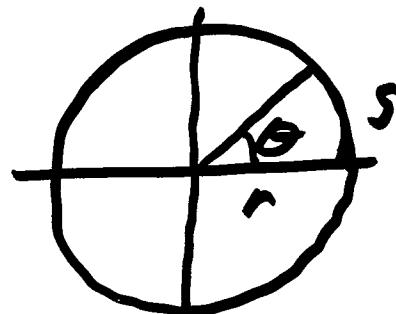
$r$  = radius

$s$  = arc length

units

$$\Theta = \frac{\text{length}}{\text{length}}$$

NO units



around circle

$$s = 2\pi r$$

$$\Theta = \frac{2\pi r}{r} = 2\pi$$

$2\pi$  radians in a circle

$2\pi$  radians =  $360^\circ$

$360^\circ$  in a circle

$$2\pi \text{ radians} = 360^\circ$$

$45^\circ$ : How many radians?

$$\frac{45^\circ}{360^\circ} \left| \begin{matrix} 2\pi \text{ radians} \\ \end{matrix} \right\rangle = \underline{\underline{\frac{\pi}{4} \text{ radians}}}$$

convert degrees to radians

Velocity increases as one moves further from center of circle

linear velocity depends on  $r$  (distance from center of circle) and how fast wheel is spinning ( $\omega$ )

$$V = \omega r$$

$$\frac{m}{s} = \frac{\cancel{\text{radians}}^{\text{degrees}}}{\cancel{s}} \cdot \omega$$

units

$$\frac{m}{s} = \frac{\cancel{\text{radians}}}{\cancel{s}} \text{ m}$$

For rotations we can also have acceleration

$$\text{linear acceleration } a_T = \frac{\Delta v}{\Delta t}$$

$$\text{angular acceleration } \alpha = \frac{\Delta \omega}{\Delta t}$$

↑  
alpha

$$V = \omega r$$

↑      ↑  
linear      angular  
velocity      velocity

related

$$\Delta v = \Delta \omega r$$

$$a_T = \frac{\Delta v}{\Delta t} = \frac{\Delta \omega r}{\Delta t} = \alpha r$$

$$\underline{a_T = \alpha r}$$

$$\text{Note } a_C = \frac{v^2}{r} = \frac{\omega^2 r^2}{r} = \omega^2 r$$

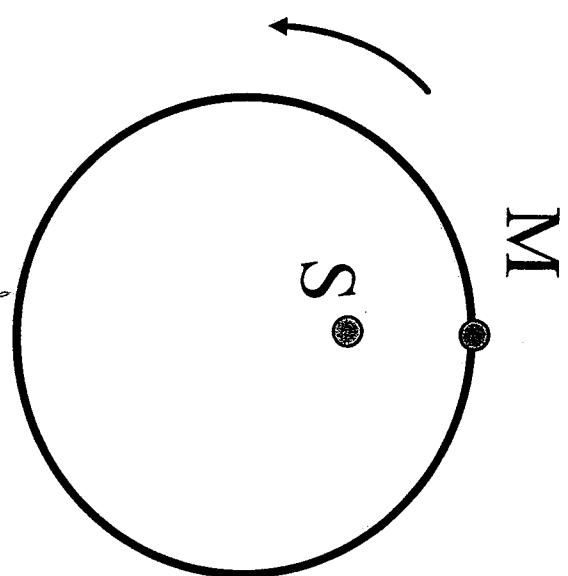
$$\underline{a_C = \omega^2 r}$$

$$a = \sqrt{a_C^2 + a_T^2}$$

## Interactive Question

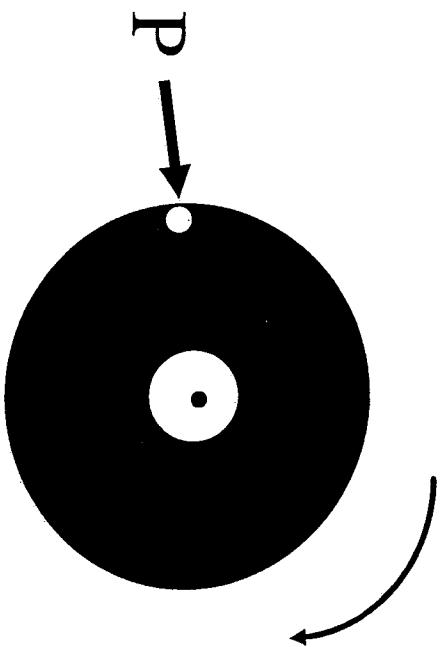
Steve (S) and his brother Mark (M) are riding on a merry-go-round as shown. Which of the following is true?

- A) They have the same speed, but different angular velocities.
- B) They have the same speed, and the same angular velocities
- C) They have different speeds and different angular velocities.
- D) They have different speeds and the same angular velocity



## Interactive Question

The record playing on the turntable is rotating clockwise as seen from above. After turning it off, the turntable is slowing down, but hasn't stopped yet. The direction of the acceleration at point P is



- A) A downward-pointing arrow.
- B) A rightward-pointing arrow.
- C) An upward-pointing arrow.
- D) A leftward-pointing arrow.
- E) A circular arrow pointing clockwise.

See very nice correspondence  
between linear variables and  
angular variables

linear      angular

$$x \leftrightarrow \theta \text{ (theta)}$$

$$v \leftrightarrow \omega \text{ (omega)}$$

$$a \leftrightarrow \alpha \text{ (alpha)}$$

linear

$$x = x_0 + v_{av} t$$

$$v_x = v_{ox} + at$$

$$x = x_0 + v_{ot} t + \frac{1}{2} at^2$$

$$v^2 = v_0^2 + 2ax$$

angular

$$\theta = \theta_0 + \omega_{av} t$$

$$\omega = \omega_0 + \alpha t$$

$$\theta = \theta_0 + \omega_{ot} t + \frac{1}{2} \alpha t^2$$

$$\omega^2 = \omega_0^2 + 2\alpha\Delta\theta$$

Need  
constant  
acceleration

Need constant  
angular  
acceleration