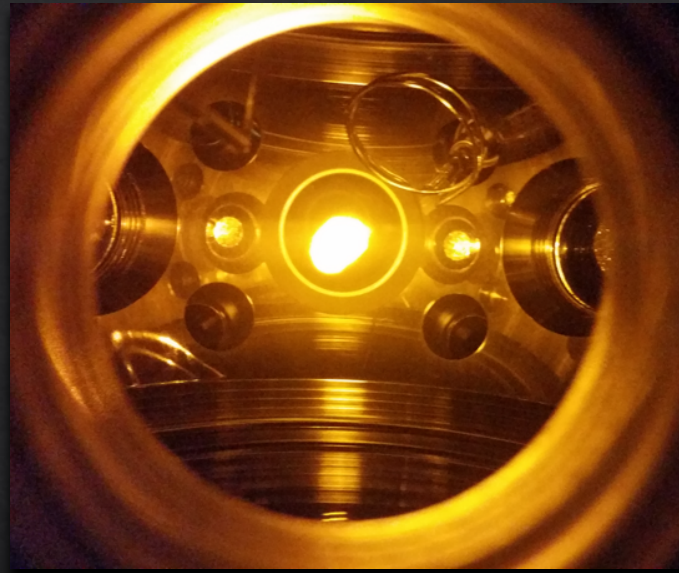


# Stabilizing laser and microwave fields for coherent control of spin-exchange collisions in ultracold sodium gases



Jeremy Norris

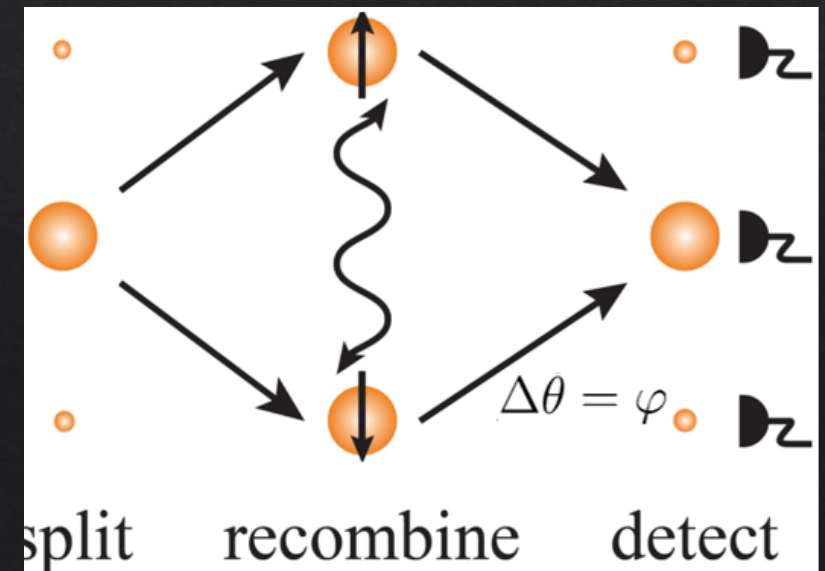
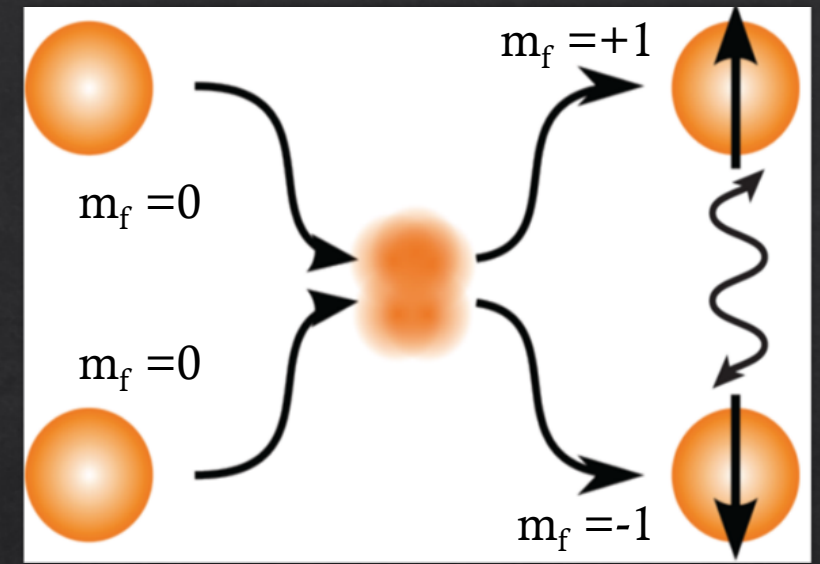
Graduate Student: Shan Zhong

Advisor: Dr. Arne Schwettmann



# Spin-exchange Collisions

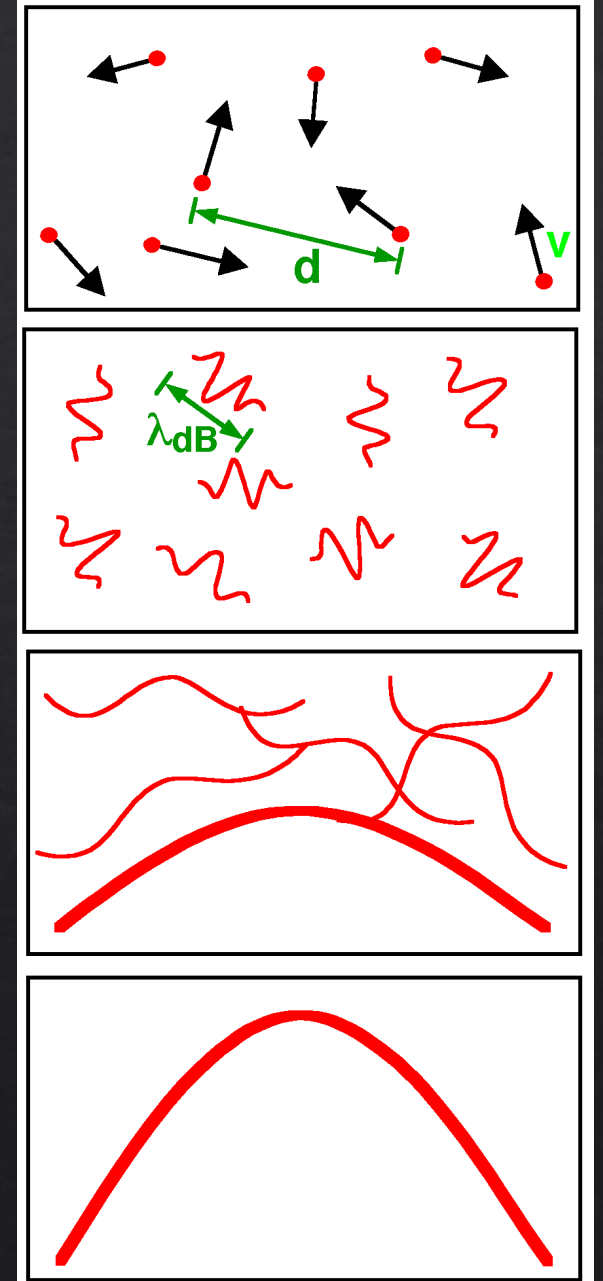
- Colliding atoms can change their spin to form entangled pairs
- Useful to build atom interferometer
- Collisions are random and uncontrollable at room temperature
- We can gain control by lowering the temperature of our sodium gas
- Coherent control is achieved by forming a Bose-Einstein condensate (BEC)





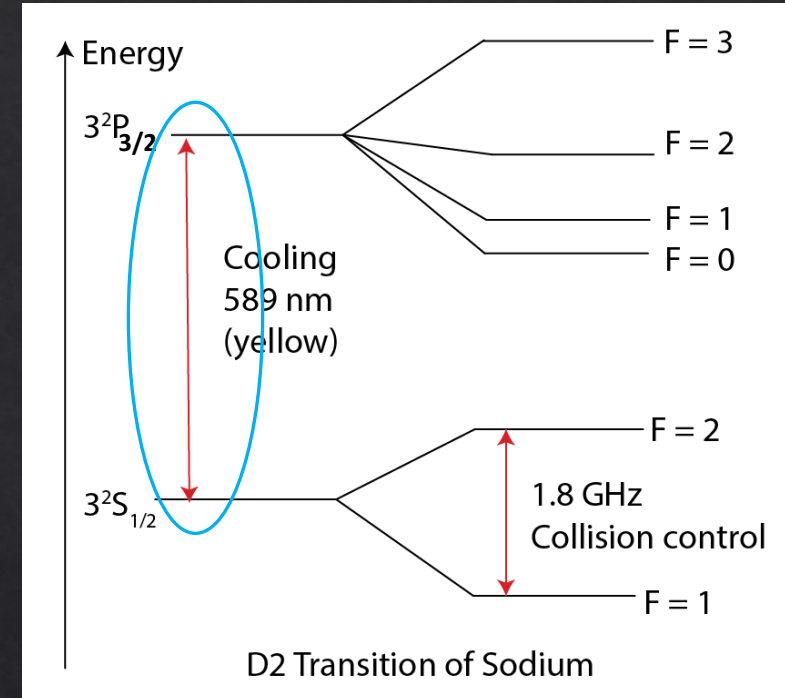
# Bose-Einstein Condensate

- At room temperature atoms behave classically
- At lower temperatures wave packets overlap
- Below critical temperature of  $\sim 100$  nK, BEC forms
- Giant matter-wave; macroscopic quantum mechanical object
- Here collisions happen controllably and coherently



# Laser Cooling of Sodium

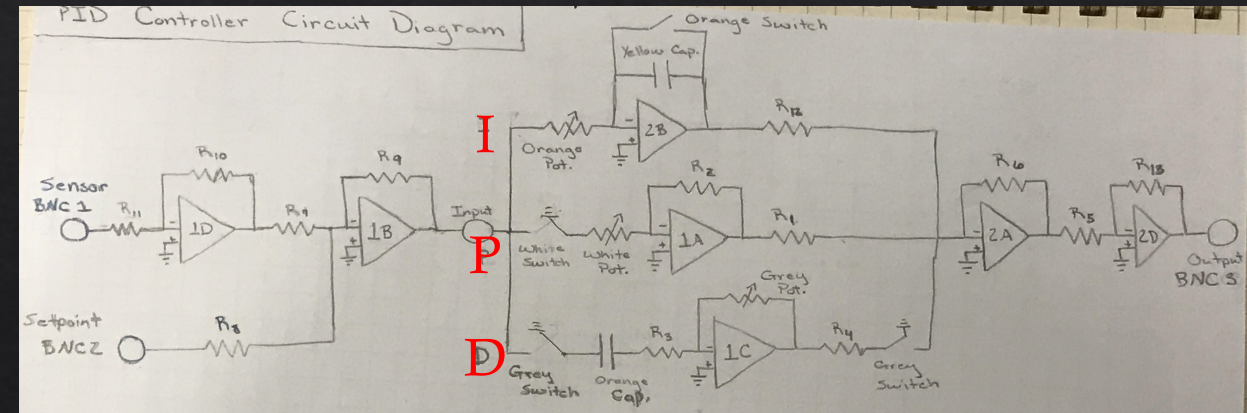
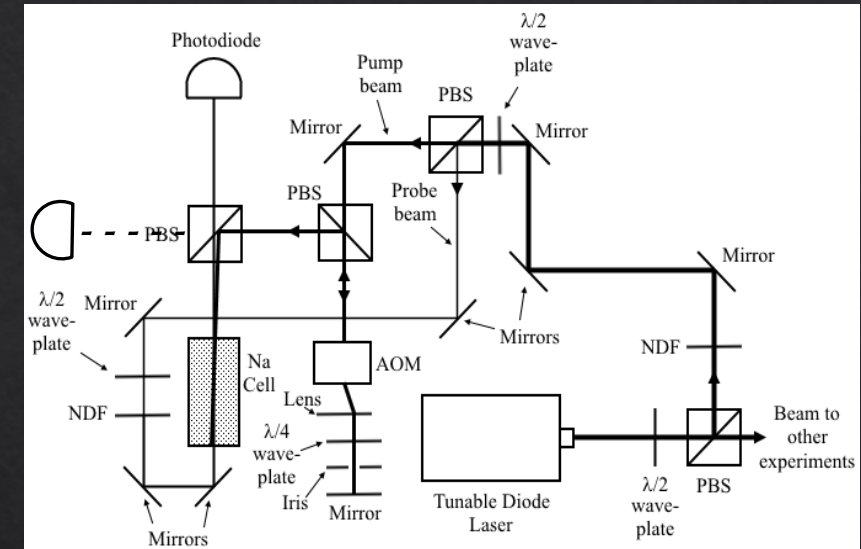
- Yellow laser at 589 nm is used to cool sodium gas
- Laser must be stabilized
- FM saturated absorption spectroscopy for stabilizing laser frequency
- Also need amplitude stabilization





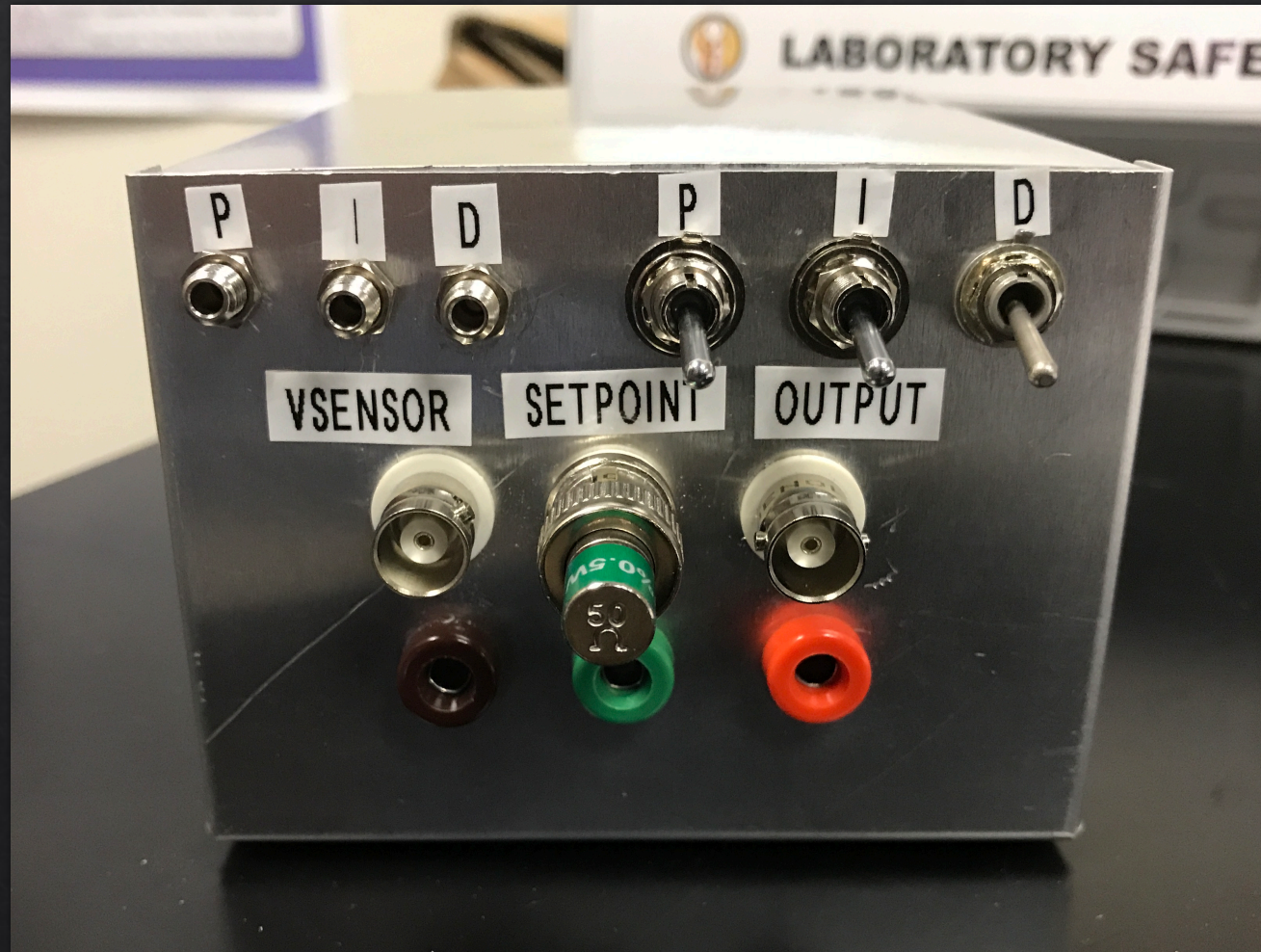
# Stabilization of Laser Amplitude

- Amplitude is measured with photodiode, adjusted using Acousto-Optic Modulator (AOM)
- Build a PID controller which is feedback loop
- Looks at measured amplitude and adjusts to reach set point
- Works like cruise control in a car
- PID: Proportional, Integral, Derivative
- Replicated existing PID controller used to stabilize laser frequency

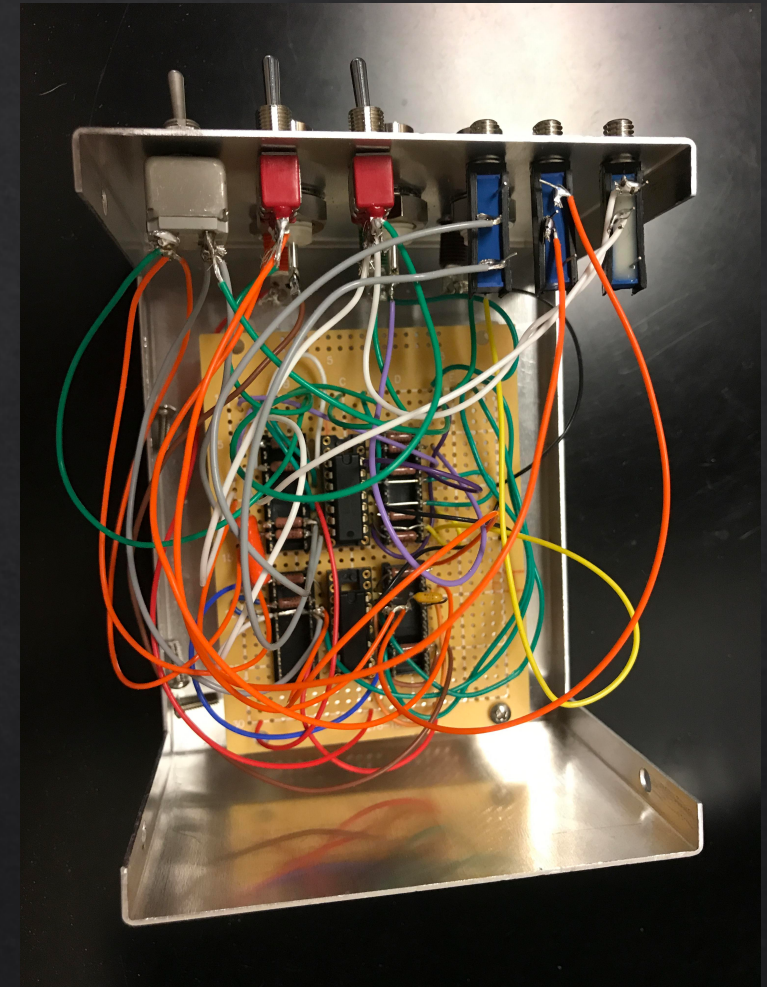




# PID Controller



Front



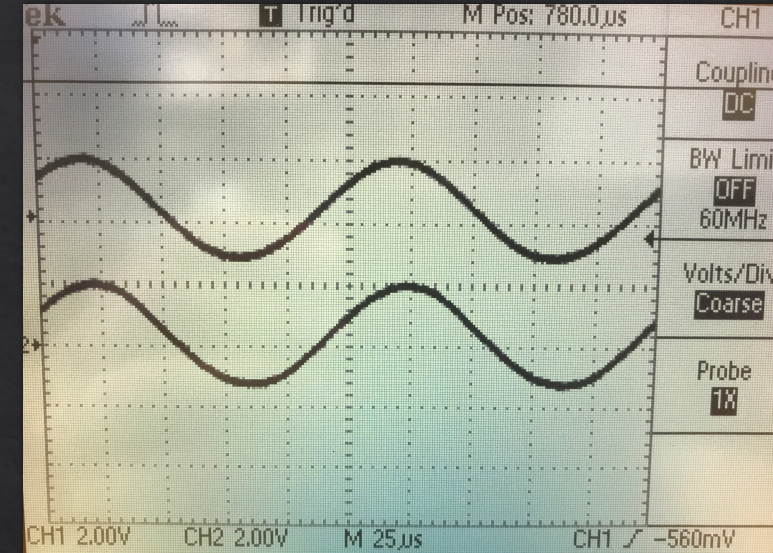
Top



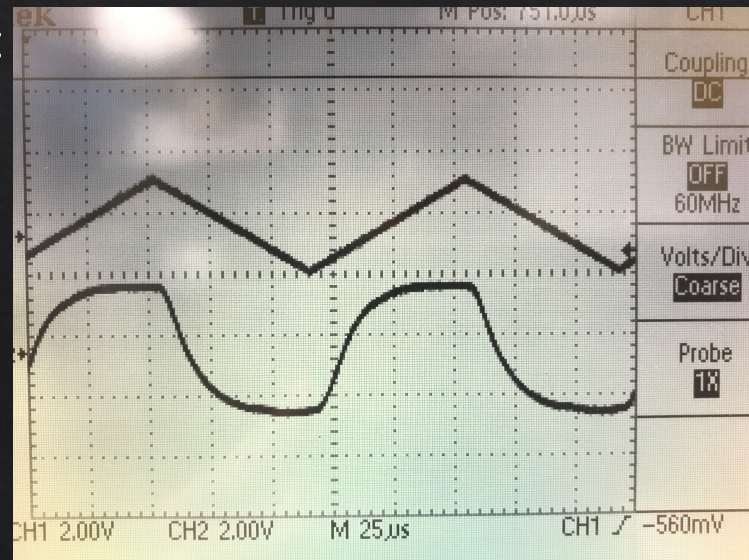
# Testing PID Controller

- Artifact due to slow speed of analog chip
- Speed is  $\sim 100$  kHz, we need response of 30 kHz (fast enough)
- Too disruptive to add to existing setup
- Laser working well enough without stabilization
- Can be added during down time

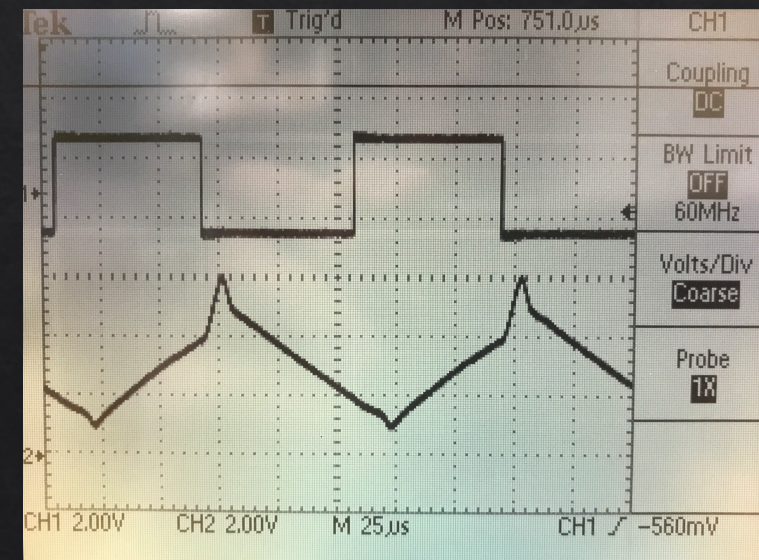
## ➤ Proportional



## ➤ Derivative



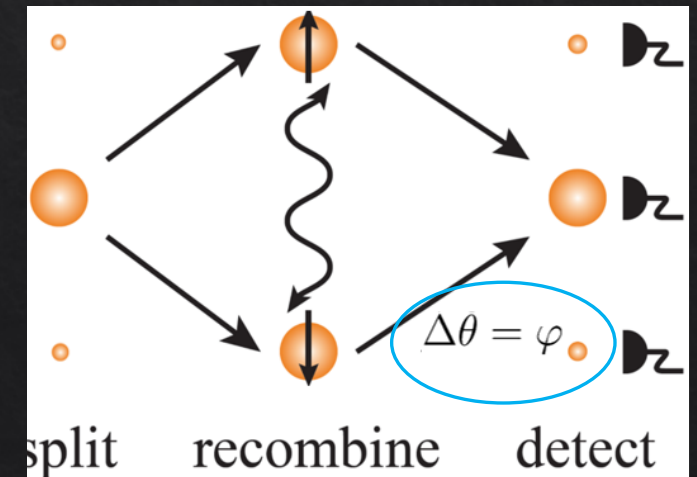
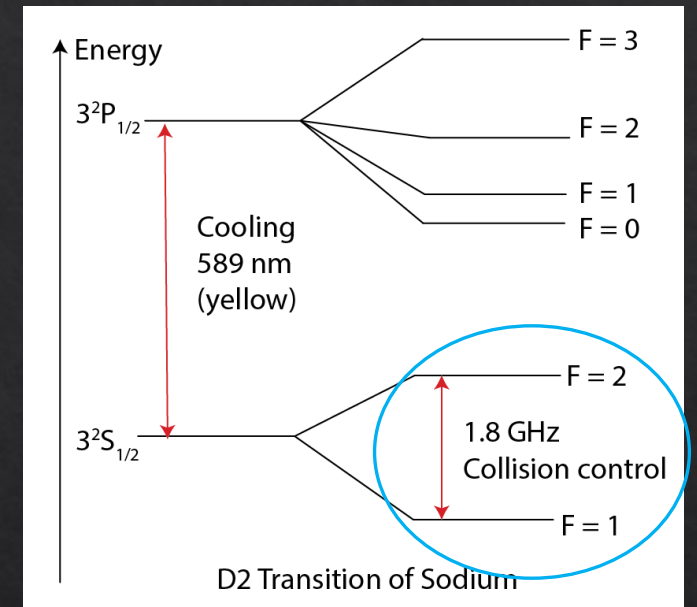
## ➤ Integral





# Microwave Control of Collisions

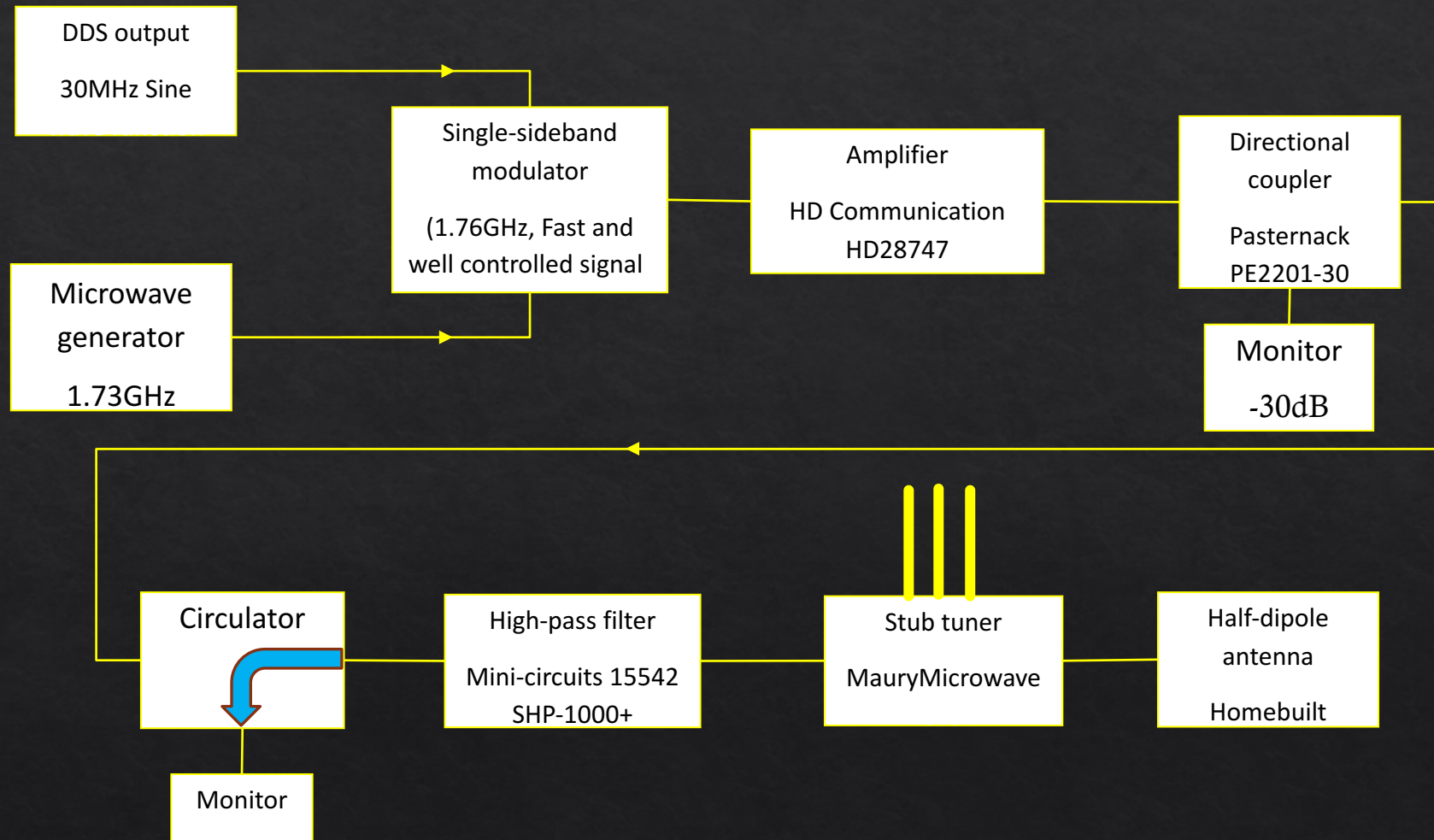
- 1.8 GHz microwaves must have fast amplitude, frequency, and phase control
- Solution is to use field programmable gate array (FPGA) that controls direct digital synthesizer (DDS)
- FPGA
  - Huge array of thousands of programmable logic gates
  - 40 digital outputs run in parallel at high speeds
  - Faster than microcontroller
- DDS
  - Dedicated chip that produces sine wave outputs with controlled amplitude, frequency, and phase

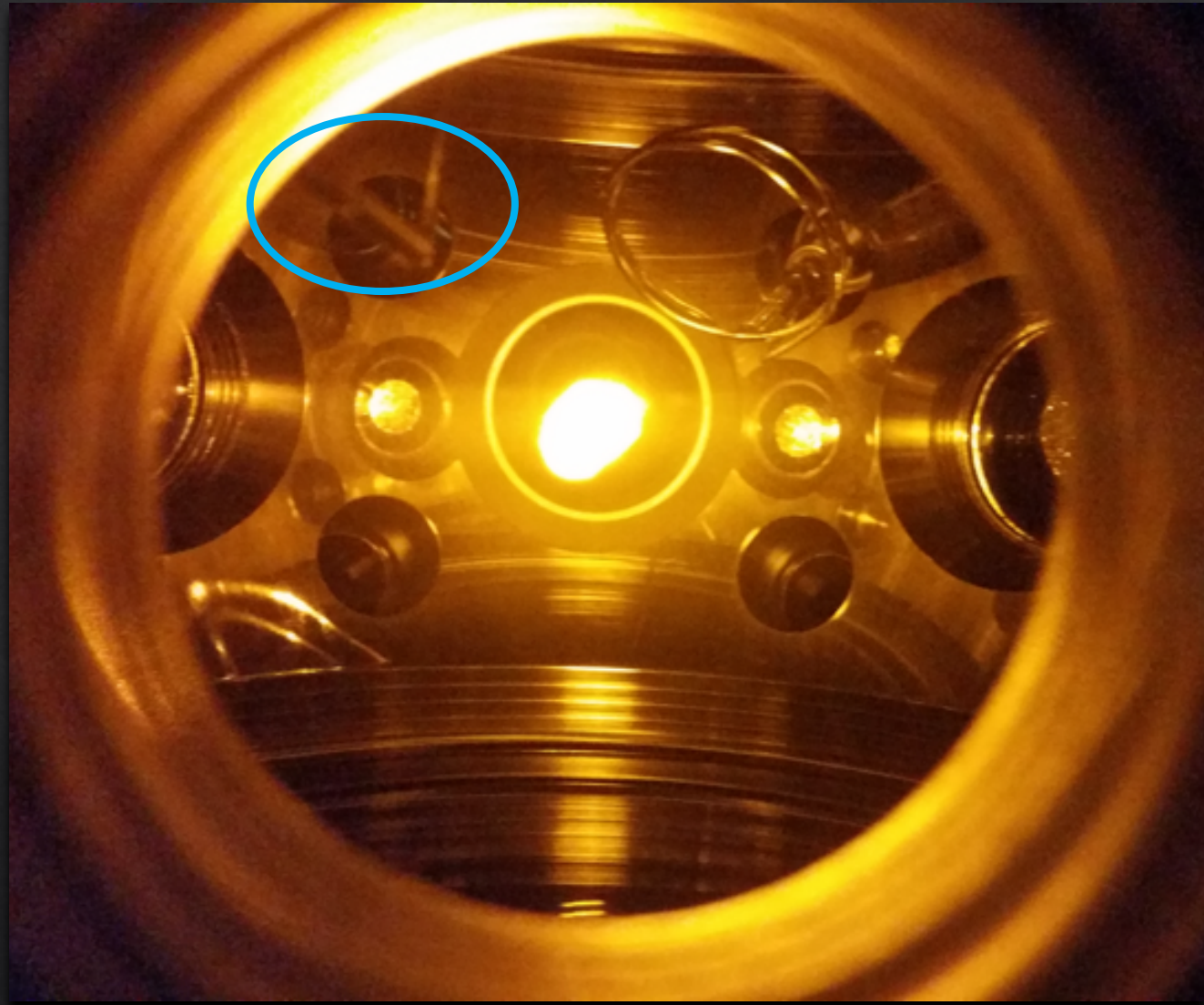




# Microwave Setup

Well controlled slow signal

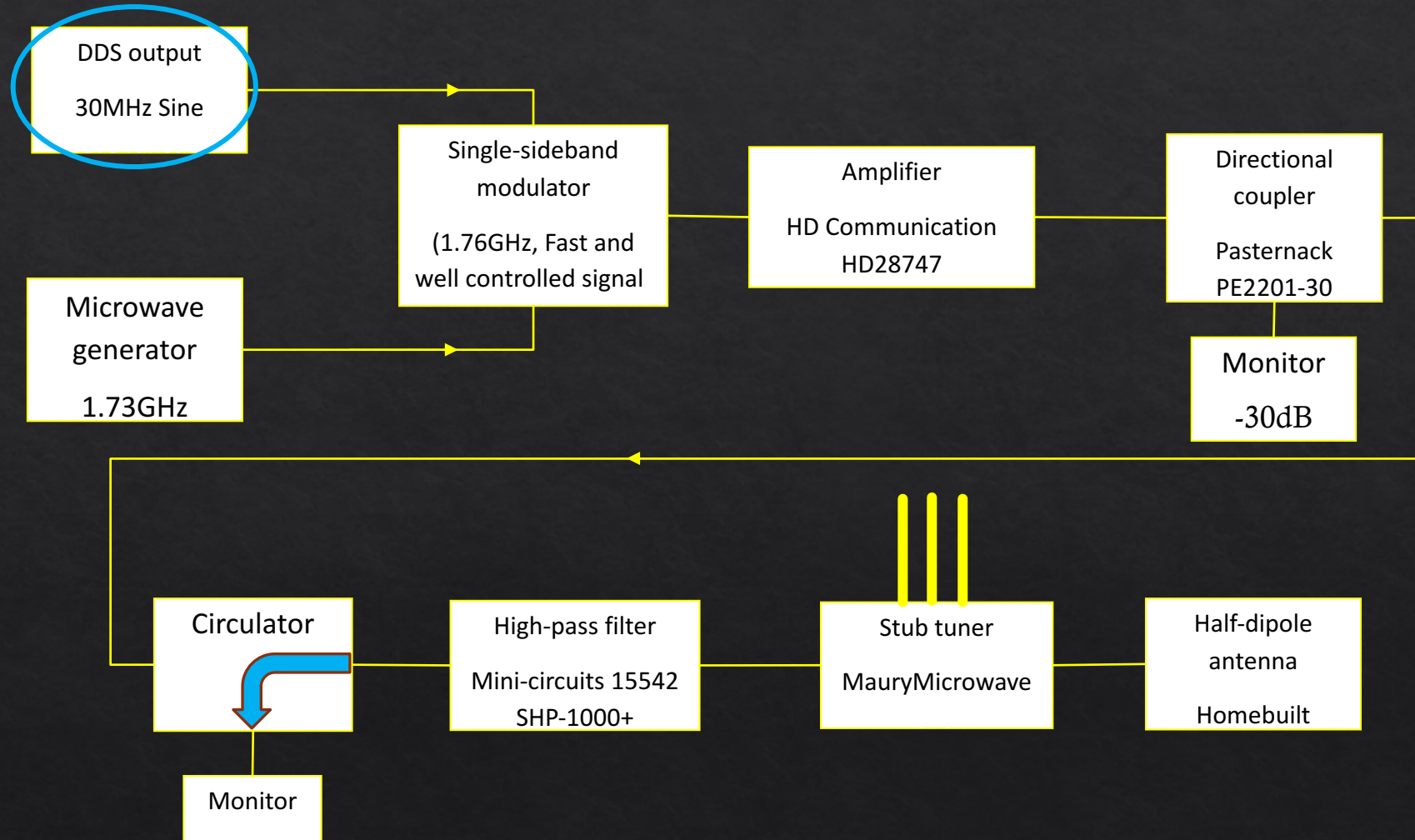






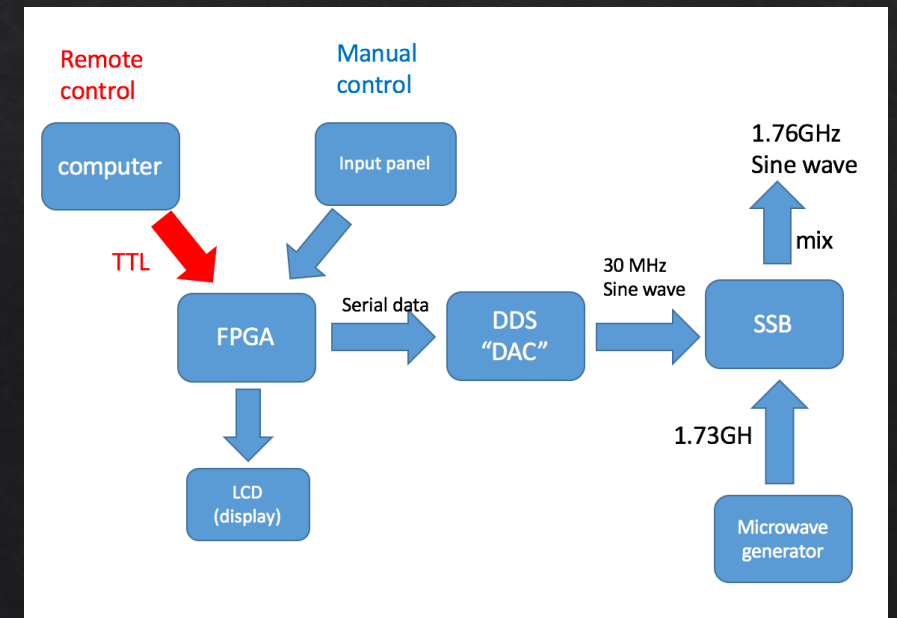
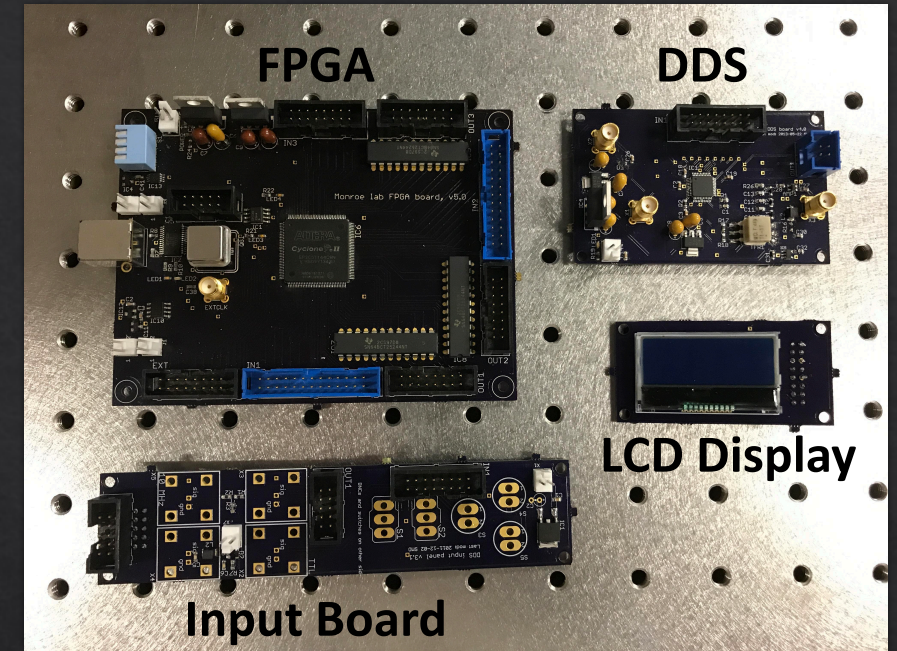
# Microwave Setup

Well controlled slow signal



# Where I Started

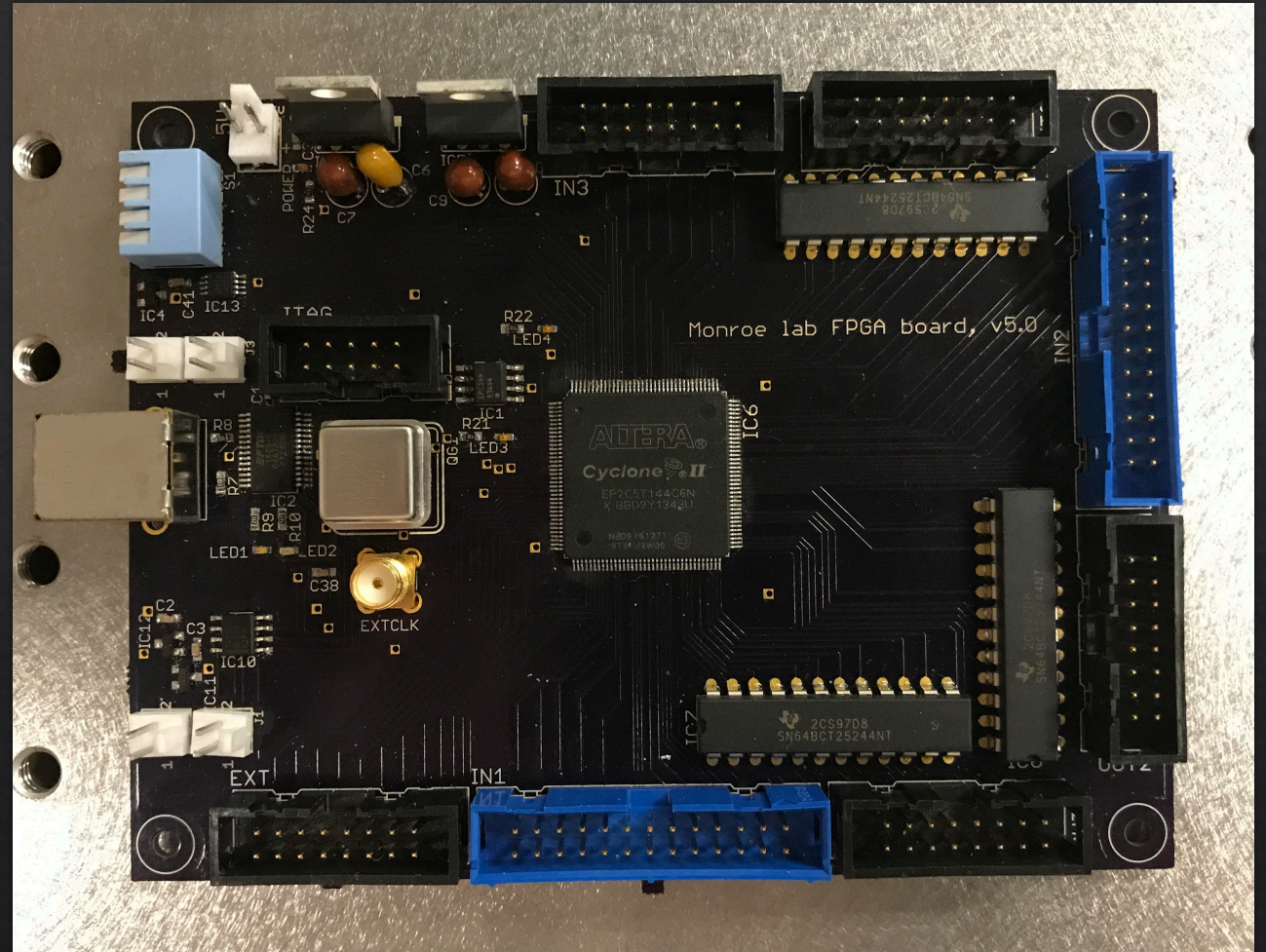
- Custom FPGA, Input, DDS and LCD Display boards
- Designs from Chris Monroe ion trapping group at University of Maryland
- IC chips and other pieces mounted by Shan Zhong
- My goal was to get these boards working





# Debugging Boards

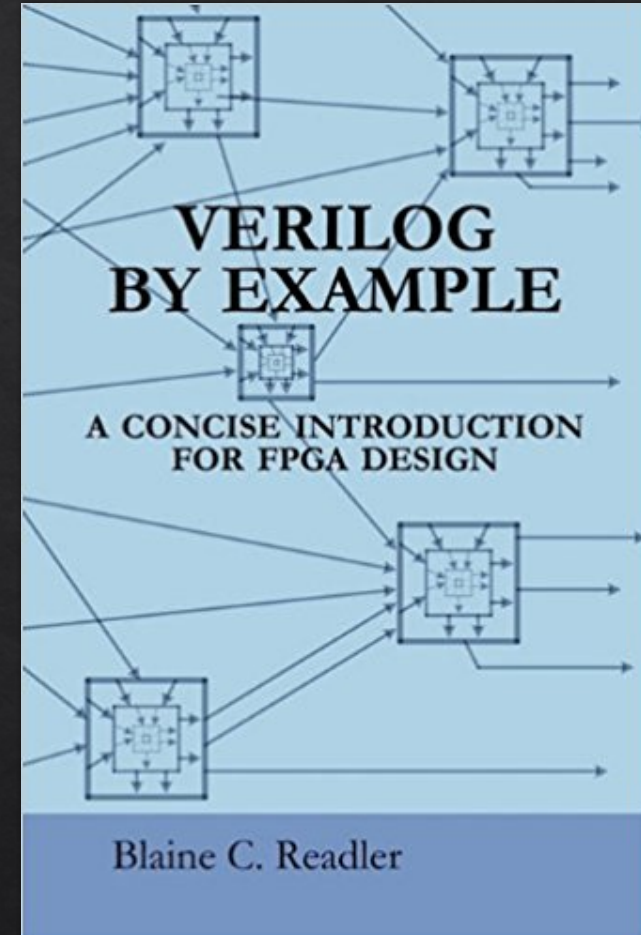
- Fixed power connections
- Touched up soldering
- Removed bridges on pins of FPGA chip
- Ordered missing parts (connectors, clock)
- Ordered USB Blaster programming device





# FPGA Programming

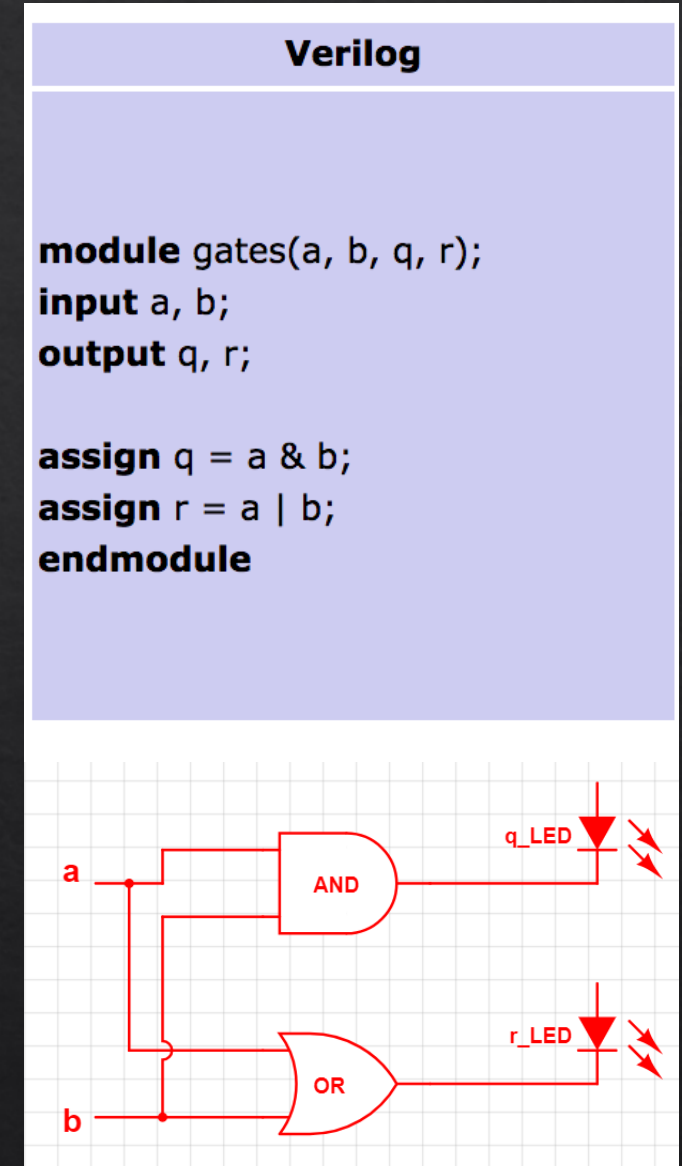
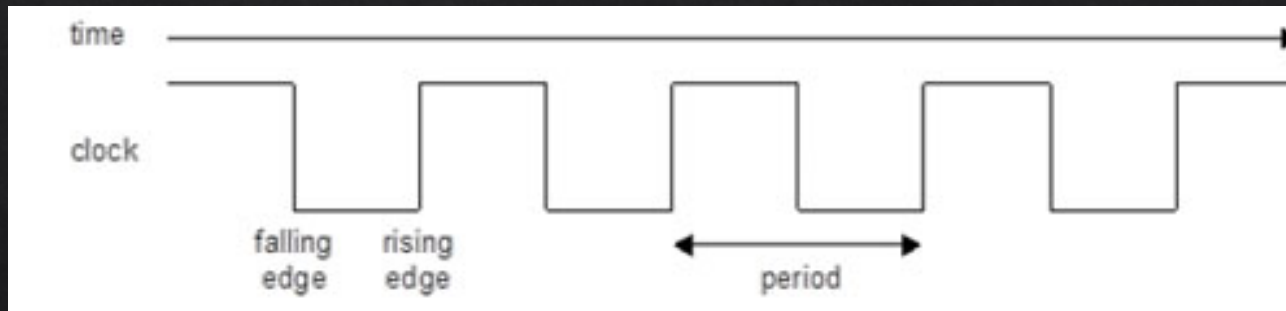
- We use a hardware description language (HDL) called Verilog
- Syntactically similar to C
- Compiles into a physically realizable system of logic gates
- Can execute multiple processes in parallel
- Learned by reading Verilog by Example





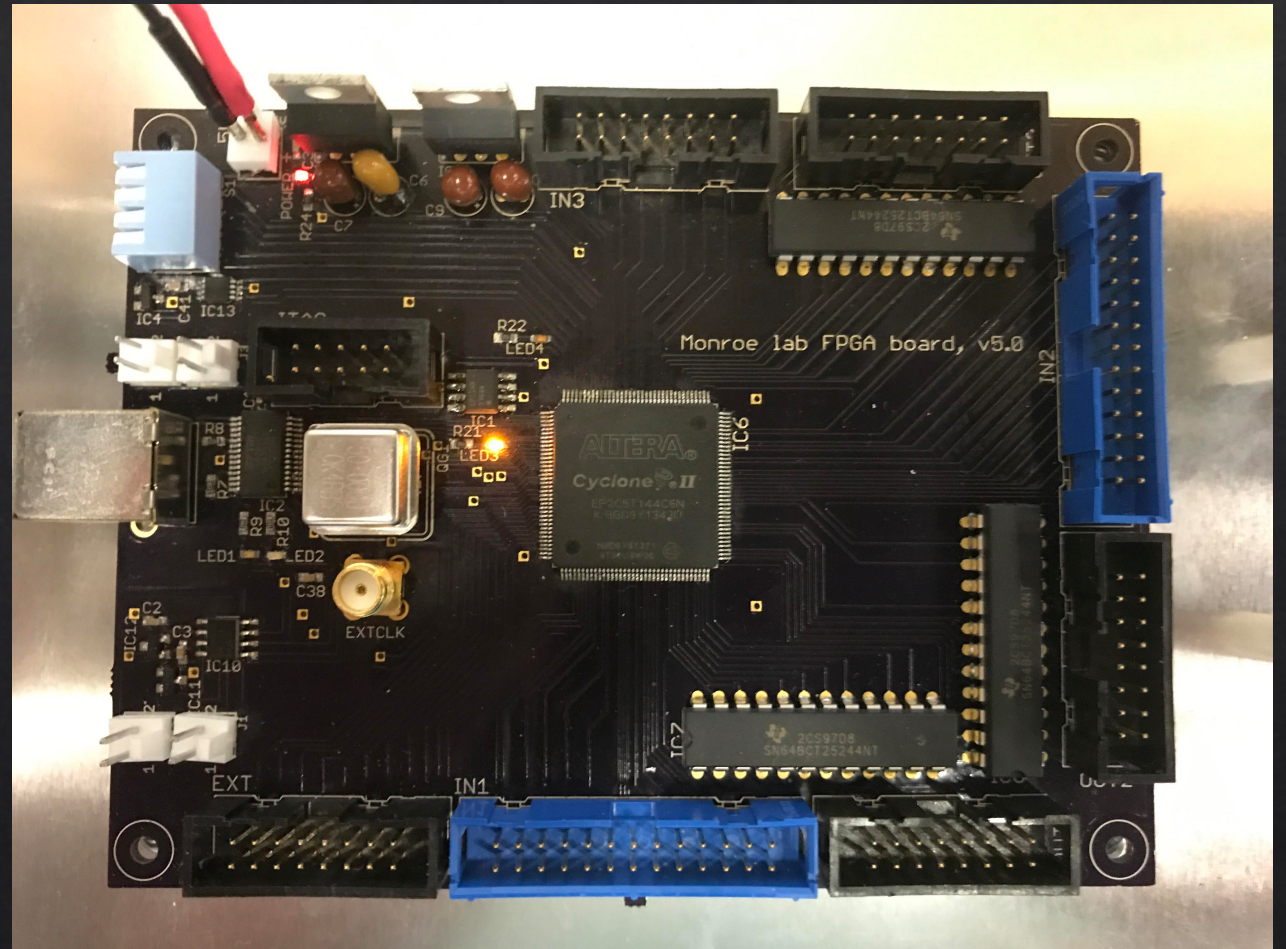
# Verilog Example

- Contained within modules
- Data types: ports (inputs/outputs), wires, registers
- Logic gates are created with “assign”
- Clocks used for timing



# Test Program

```
aom_driver.v x dds_write.v x led_test.v x manual_freq.v x fifo_write.v x lcd_
1 //
2 // This is a test module for a Cyclone II FPGA.
3 //
4
5 // Module and ports
6 module led_test(
7     clk,
8     led);
9
10 // Assign inputs and outputs
11 input clk; // 50 MHz clock
12 output led;
13
14 reg [31:0] counter;
15
16 // LED is toggled using the 23rd bit of the counter
17 assign led = counter[22];
18
19 always @(posedge clk)
20 begin
21     counter <= counter + 1;
22 end
23
24 endmodule
```





# Compiler

- We use Quartus II software by Altera
- Compile code and assign pins
- Download program via USB to JTAG port
- JTAG is debugging port which all chips have
- Can also be used to program



# Source Code

- We are using source code written by Steve Olmschenk from Joint Quantum Institute
- Program with full software for microwave control
- Designed to control DDS to produce 30 MHz sine wave
- Allows manual and remote control of signal using LabVIEW on computers in lab
- I added documentation to code package

```
reg    [3:0]  freqChange; // determines how to change the frequency
reg    [2:0]  step;       // step in changing the frequency
reg    [1:0]  convStep;   // step in converting from binary to BCD
reg    [23:0] waitCnt;    // counter to wait some time between triggers

parameter MHz      = 32'h00A3D70A;
parameter kHz      = 32'h000029F1;

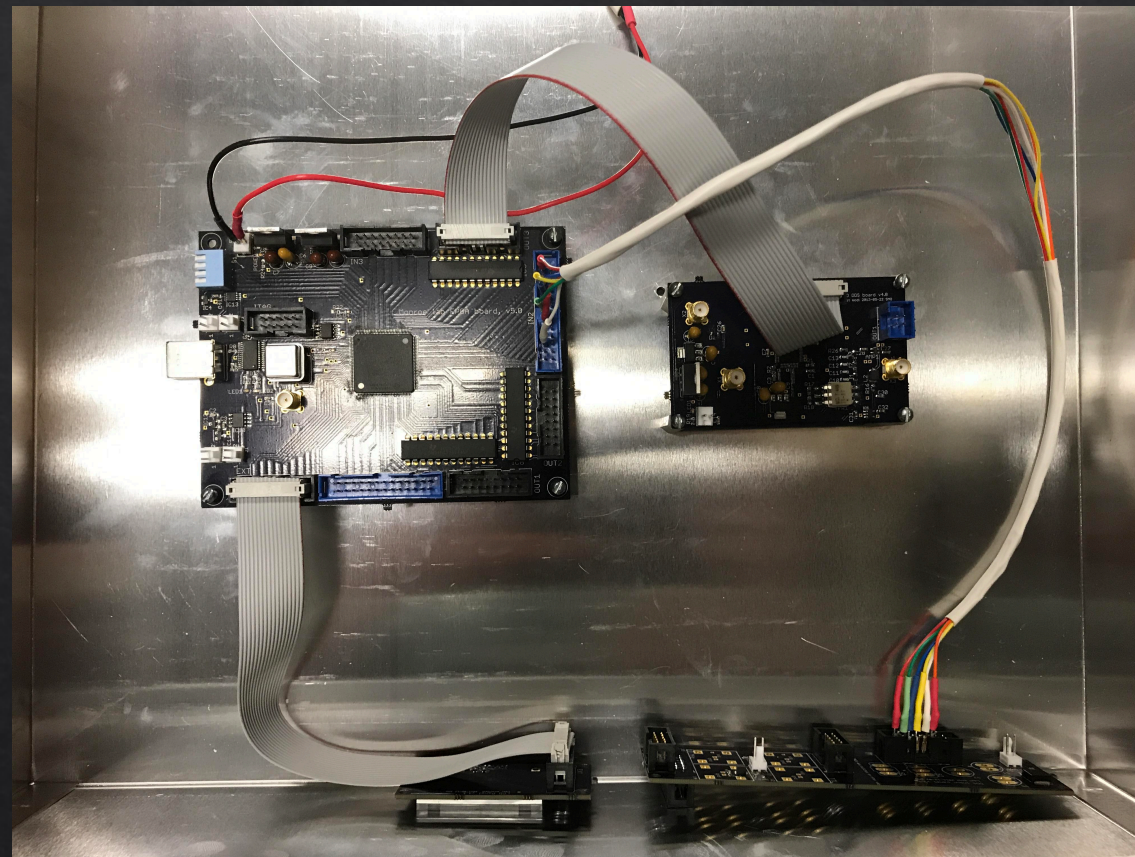
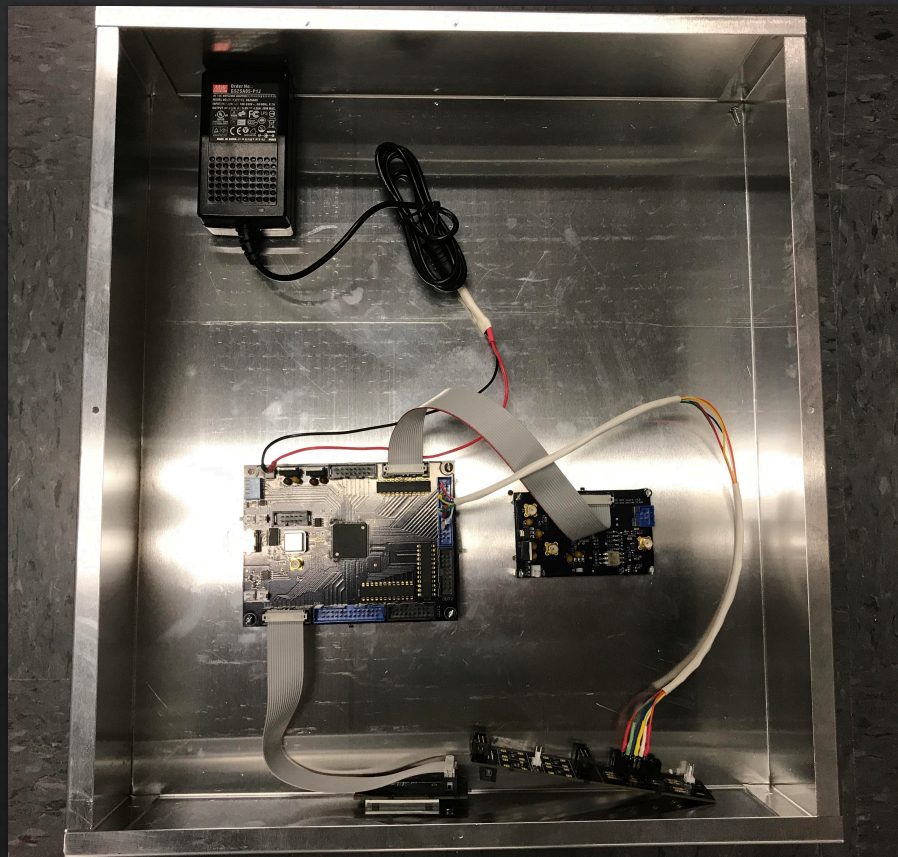
always @(posedge clk)
begin
    freqChange <= {(active == 4'h0), (active == 4'h1), trigup, trigdown};

    case (step)
    0: // look for frequency change trigger
        case (freqChange)
        4'b0110: // +1 kHz
            begin
                if (freqDDS <= (32'h7FFFFFFF - kHz)) // check tha
                begin
                    freqDDS <= freqDDS + kHz; // increases freq
                    freqBIN <= freqBIN + 1;  // same as above
                end
            end
        endcase
    endcase
end
```

Example from a module in source code



# Enclosure





# Conclusion:

- I learned skills associated with building and debugging electronic circuits
- I learned how to program hardware using Verilog
- Successfully built a working PID controller that can serve as a feedback loop for amplitude stabilization
- Powered and programmed the FPGA board
- Began building an enclosure for mounting and housing the FPGA board and other components needed for the microwave generation



# Outlook:

- PID controller can be implemented in the future if additional stabilization is needed
- Use FPGA and DDS to output 30 MHz sine wave
- Upon reaching BEC, FPGA controlled microwave pulses will allow for matter-wave interferometry experiments

**Thank you.**

Questions?





